

PyTUQ: Python Toolkit for Uncertainty Quantification

<https://github.com/sandialabs/pytuq>

Authors: Khachik Sargsyan, Bert Debusschere, Emilie Grace Baillo

Dependencies: numpy, scipy, matplotlib, (pytorch, dill, quinn)

License: BSD 3-Clause License



main	7 Branches	1 Tag	Go to file	Code
eebaill	Merge pull request #15 from sandialabs/12-adding-readme-badges...	94b120a · 2 months ago	27 Commits	
.github/workflows	Updating coveralls badge and workflow	2 months ago		
apps	adding optimization modules. Also some minor comment...	3 months ago		
contributed/dakota_examples	PyTUQ initial package commit	7 months ago		
docs	Updating badges and versioning call in Sphinx docs	2 months ago		
examples	added multiindex growth capability (ported from UQtk, a...	2 months ago		
src/pytuq	added multiindex growth capability (ported from UQtk, a...	2 months ago		
tests	PyTUQ initial package commit	7 months ago		
.gitignore	Initial commit	7 months ago		
LICENSE	PyTUQ initial package commit	7 months ago		
README.md	Updating coveralls badge and workflow	2 months ago		
pyproject.toml	Added pytest unit testing to GH actions and setup file	2 months ago		
requirements.txt	PyTUQ initial package commit	7 months ago		

READMELicense

Python Toolkit for Uncertainty Quantification (PyTUQ)

About

Python Toolkit for Uncertainty Quantification

sandialabs.github.io/pytuq/

regressionbayesian-inferenceuncertainty-quantificationuqinverse-problems sparse-regression surrogate-models forward-propagation surrogates snl-science-libs snl-other snl-data-analysis model-error scr-3177

ReadmeView licenseActivityCustom properties7 stars4 watching0 forksReport repository

Releases1

v1.0.0 Latest on Apr 11

FASTMATH

SciDAC-5 FASTMath Institute

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Research Areas

AI/ML Capabilities

Resources for SciDAC Partnerships

Science Partnerships

PyTUQ

The Python Toolkit for Uncertainty Quantification (PyTUQ) is a lightweight Python library for a range of uncertainty quantification tasks and workflows. Features include conventional tools such as polynomial chaos machinery with mixed bases, global sensitivity analysis, quadrature point generation, linear regression, Bayesian inference with various flavors of Markov chain Monte Carlo. PyTUQ also includes advanced methods such as Bayesian compressed sensing, sampling-based Rosenblatt transformation and embedded model error calibration.

PyTUQ was released on github in March 2025 under a BSD 3-Clause License. It has been used for various SciDAC partnership applications ranging from fusion to materials science to earth system modeling, as well as for the UQ needs of land modeling components of the DOE E3SM project.

DOWNLOAD SITE



CONTACT

Khachik Sargsyan
Sandia National Laboratories

[Send email](#)

How PyTUQ was born

- Had a need and started coding a mixed-bases PC. Later KL kicked in... hence the pre-release name KLPC.
- Collaborators requesting little pieces of UQ codes here and there.
- Increasingly more Python usage and less willingness to cmake.
- My own allergy for rewriting the same code twice:
if I needed to, it was better to write a library.
- Not intended to comprehensively cover all methods:
add functionality as needed.
- All key UQ functionalities written with OOP principles, with base classes:
(supposed to be) easily extendable.
- Released March 2025
- Part of SciDAC-6 FASTMath Software catalogue

Current usage

- BER: E3SM Land Model UQ
Reduced-dimensional surrogate, calibration,
embedded model error, GSA
- BER Partnership: Quasi-biennial Oscillation
- BES: Exascale Catalytic Chemistry
Stochastic surrogate, GSA,
covariance estimation
- FES Partnership: ThermChem-FW
Linear regression,
Uncertainty propagation, GSA
- Interlab LDRD: Radiography UQ
Optimization, Inference/MCMC
-

Overall Structure

Outer-loop utilities



Tests



Examples



Apps



Contributed

Core library packages



func



rv



fit



lreg



linred



optim



minf



utils



workflows



surrogates



Docs

- <https://sandialabs.github.io/pytuq/>
- (Almost) all commented with docstrings
- Mathy details lacking
- Documentation in progress

PyTUQ

Search docs

GETTING STARTED

- Installation
- About

API REFERENCE

- Section Navigation

EXTRA

- Index

PyTUQ Documentation

View page source

tests Run Tests passing Deploy to GitHub Pages passing coverage 10%

Last Updated: Jul 31, 2025

Version: 1.0.0

Hello, **PyTUQ** is a Python-only toolkit for uncertainty quantification in computational models. To explore the modules offered by PyTUQ, use the navigation panel on the left or below.

Check out the [Getting Started](#) section for further information, including how to [install](#) the project.

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lreg

Base classes
Extendable



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Getting Started

- [Installation](#)



Tests with minimal sanity checks

test_composefcn.py

test_diam.py

test_dom.py

test_gmm.py

test_hess.py

test_mi.py

- Meant to be run out of the box
- *pytest* which automatically runs all *test_*.py* files
- Produces no screen output, only assertion checks
- Supposed to have *test_*.py* for any new capability
(except I gravitate toward example *ex_*.py* instead of a test)
- Not too many currently



Examples of varying complexity

<code>ex_bcs*.py</code>	<u>Bayesian Compressive Sensing</u>
<code>ex_gp.py</code>	Gaussian Process regression
<code>ex_gsa*.py</code>	Global Sensitivity Analysis
<code>ex_*ros*.py</code>	<u>(Inverse) Rosenblatt transform</u>
<code>ex_kl*.py</code>	Karhunen-Loève decomposition
•	•
•	•
•	•
<code>ex_lreg*.py</code>	Linear regression
<code>ex_mcmc*.py</code>	Markov chain Monte Carlo
<code>ex_minf*.py</code>	<u>Embedded model error inference</u>
<code>ex_pcrv.py</code>	PC multivariate random variable
<code>ex_uprop.py</code>	Uncertainty propagation
•	
•	
•	



Examples of varying complexity

ex_evidence.py
ex_func.py*
ex_integrate.py
ex_genz1d.py
ex_mindex.py*
•
•
•
ex_optim.py
ex_mixture.py
ex_quad.py
ex_sampling.py
ex_slice.py

•
•
•

- Meant to be run out of the box
- Usually refer to one of these if requests come
- ... or write a quick one per request
- Produce screen outputs, and *.png* (and some *.txt*) files
- Script to run all examples together

```
run_examples.sh
1  #!/bin/bash -e
2
3  mkdir -p runex
4  cd runex
5
6  SCRDIR=$(dirname "$0")
7
8
9  echo $SCRDIR
10 for ex_scr in "$SCRDIR"/../examples/*.py; do
11     echo "=====
12     start=$SECONDS
13     ex_scr_name=$(basename "$ex_scr" .py)
14     echo "Running $ex_scr"
15     "$ex_scr" > ${ex_scr_name}.log
16     duration=$(( SECONDS - start ))
17     echo "It took $duration sec."
18     #echo "=====
19 done
20
```




Apps and workflows

kl_fit.py

KL fit given data

kl_surr_fit.py

KL+PC/NN surrogate

wf_uqpc.x

pc_prep.py

pc_sam.py

pc_fit.py

Workflow for PC-based propagation

nn_fit.py

NN surrogate. Quick and dirty.

Relies on QUiNN library <https://github.com/sandialabs/quinn>

mr_run.py

Multithreading app:

Creates folders and runs a list of command lines

plot_cov.py

plot_pcoord.py

plot_pdfs.py

plot_xx.py

plot_yx.py

Plotting apps

- Typically command-line arguments and works as-is.
- Similar to command line ‘apps’ in UQTK.
- A few more we currently have outside PyTUQ, waiting to be documented.

Contributed packages/modules



Dakota wrappers

Room for external contributions



src

Core library packages



func

Multivariate functions

$$f: \mathbb{R}^d \rightarrow \mathbb{R}^o$$



rv

Multivariate random variables (PCRV, GMM, ...)



lreg

Linear regression (ANL, LSQ, BCS, ...)



fit

Nonlinear fits (GP)



gsa

Global sensitivity analysis (Sobol, PC, MOAT, ...)



linred

Linear dimensionality reduction (PCA, KLE, ...)



optim

Optimization (GD)



minf

Model inference (Bayes/MCMC/Embedded Model error)



utils

Plotting, data manipulation, ...



workflows

Utilities chaining a few tasks



surrogates

Surrogate wrappers



func

Function package

func.py

benchmark.py

genz.py

toy.py

poly.py

chem.py

oper.py

- Parent function class
- Multivariate, multioutput functions $f: \mathbb{R}^d \rightarrow \mathbb{R}^o$
- Lots of benchmark functions
- Gradients/Hessians
- Operations on functions
- Plotting routines of various slices
- See *ex_func.py* and *ex_funcgrad.py*

```
Fcn1 = benchmark.Ishigami()
Fcn2 = benchmark.Branin()
Fcn = Fcn1 * Fcn2
Fcn.grad(x)
Fcn.plot_2d(d1, d2)
```

```
pcrv = PCRv(nout, ndim, pctype)
[pcfit via e.g. linear regression]
pcrv.setFunction()

newfcn = pcrv.function + benchmark.Ishigami()
```



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Function package:

- My son Vahan kept bugging me for a home summer code/math project.

side story





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- and implement common benchmark functions

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- Also compute by hand and implement analytical gradients (win-win for a father).

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- **After a few (4-5)**, he lost motivation and approached me to ask for money.
- We converged at \$10/function and the money goes to his next guitar purchase...
(again, a win-win for a father, and money laundering of sorts).
- ... including gradients and documentation python/sphinx/latex style, and of course, tests





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- ... including gradients and documentation python/sphinx/latex style, and of course, tests
- **After a few more (8-10)**, he got bored again
(he probably thought he should have asked for more money).
- So he wrote a Latex-to-Python interpreter/converter (took a couple of weeks)
that auto-writes the PyTUQ code given a latex string of the formula.





Function package: side story

<https://github.com/Vahanosi4ek>

Files

main

Go to file

>

__pycache__

>

benchmark

>

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benchmark.py

benchmark_nn.py

benchmark_nn_test.py

benchmark_test.py

>

latex_compiler

>

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main.py

nodes.py

optimizer.py

parser.py

tree_manip.py

.gitignore

LICENSE

README.md

pytuq_funcs / benchmark / benchmark.py

Vahanosi4ek more funcs

Code

Blame

3440 lines (2535 loc) · 127 KB

1

#!/usr/bin/env python3

2

3

import numpy as np

4

from pytuq.func.func import Function

5

6

TODO: add complete support for discontinuous and nondifferentiable functions

7

8

https://infinity77.net/global_optimization/test_functions.html#test-function

9

1-d functions

10

11

<div>class SineSum(Function):</div>

12

<div>"""</div>

13

<div>Problem 02 [https://infinity77.net/global_optimization/test_functions_1d.h</div>

14

<div>"""</div>

15

<div>def __init__(self, c1=1., c2=10/3, name="SineSum"):</div>

16

<div>super().__init__(</div>

17

<div>self.name = name</div>

18

<div>self.c1, self.c2 = c1, c2</div>

19

<div>self.dim = 1</div>

20

<div>self.outdim = 1</div>

21

<div></div>

22

<div>self.setDimDom(domain=np.ones((self.dim, 1)) * np.array([2.7, 7.5]))</div>

23

<div></div>

24

<div>def __call__(self, x):</div>

25

<div>r"""Simple sum of sines</div>

26

<div></div>

27

<div>.. math::</div>

28

<div>f(x)=\sin(c_1x)+\sin(c_2x)</div>

29

<div></div>

30

<div></div>

31

<div>Default constant values are :math:`c = (1., 10/3)`.</div>

32

<div></div>

33

<div>Args:</div>

34

<div>x (np.ndarray): Input array :math:`x` of size `(N,1)`.</div>

35

<div></div>

36

<div>Returns:</div>

37

<div>np.ndarray: Output array of size `(N,1)`.</div>

38

<div>"""</div>

39

<div>return np.sin(self.c1 * x) + np.sin(self.c2 * x)</div>

40

<div></div>

41

<div>def grad(self, x):</div>



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```
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Ackley(),
Adjiman(),
Alpine01(),
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AMGM(),
BartelsConn(),
Bird(),
Bohachevsky(),
Branin01(),
Branin02(),
Brent(),
Bukin02(),
Bukin04(),
Bukin6(),
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Damavandi(),
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Dolan(),
EggCrate(),
ElAttarVidyasagarDutta(),
FreudensteinRoth(),
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Mishra06(),
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Price03(),
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Quadratic(),
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Schaffer01(),
Schaffer02(),
Schaffer04(),
# SchmidtVetters(), X
Schwefel36(),
SixHumpCamel(),
ThreeHumpCamel(),
Treccani(),
Trefethen(),
Ursem01(),
Ursem03(),
# Ursem04(), X
UrsemWaves(),
VenterSobieszczzanskiSobie
WayburnSeader01(),
WayburnSeader02(),
Wolfe(),
Zettl(),
Zirilli(),
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CrossInTray(),
DropWave(),
EggHolder(),
Griewank(),
# Trig
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Forrester(),
Friedman(),
GramacyLee(),
GramacyLee2(),
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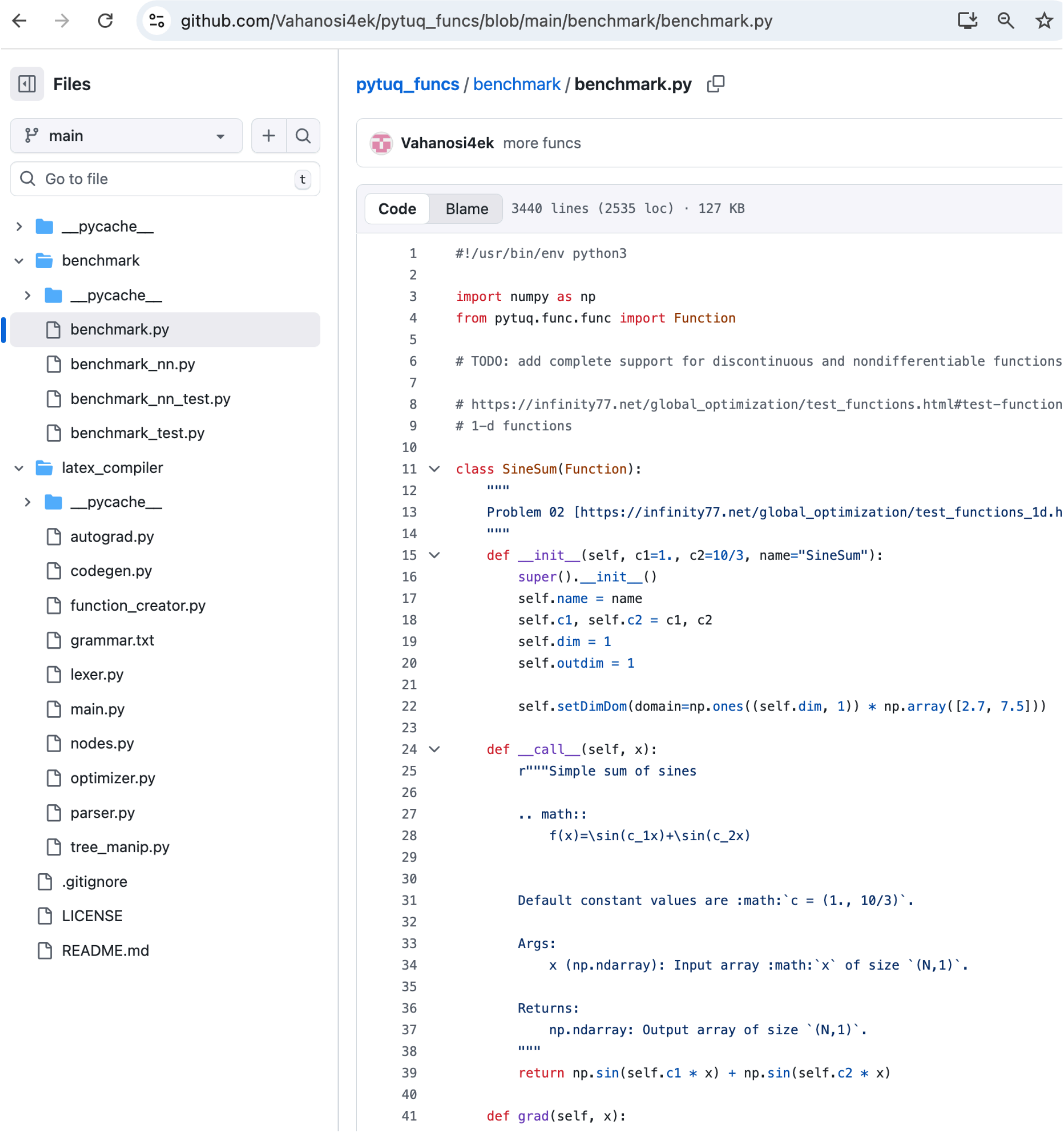
He now has about 100
functions, ready to be forked
and merged to PyTUQ.
Will do soon. School just
started.

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I paid with bonus, we brought back a \$3k guitar from Spain:)



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# SchmidtVetters(), X
Schwefel36(),
SixHumpCamel(),
ThreeHumpCamel(),
Treccani(),
Trefethen(),
Ursem01(),
Ursem03(),
# Ursem04(), X
UrsemWaves(),
VenterSobieczcczanskiSobie
WayburnSeader01(),
WayburnSeader02(),
Wolfe(),
Zettl(),
Zirilli(),

# Many local minima (it's wor
CrossInTray(),
DropWave(),
EggHolder(),
Griewank(),

# Trig
ChengSandu(),
Sine1d(),
Forrester(),
Friedman(),
GramacyLee(),
GramacyLee2(),
```


https://github.com/Vahanosi4ek/pytuq_funcs/blob/main/benchmark/benchmark.py

Files

main

Go to file

__pycache__

benchmark

__pycache__

benchmark.py

benchmark_nn.py

benchmark_nn_test.py

benchmark_test.py

latex_compiler

__pycache__

autograd.py

codegen.py

function_creator.py

grammar.txt

lexer.py

main.py

nodes.py

optimizer.py

parser.py

tree_manip.py

.gitignore

LICENSE

README.md

pytuq_funcs / benchmark / benchmark.py

Vahanosi4ek more funcs

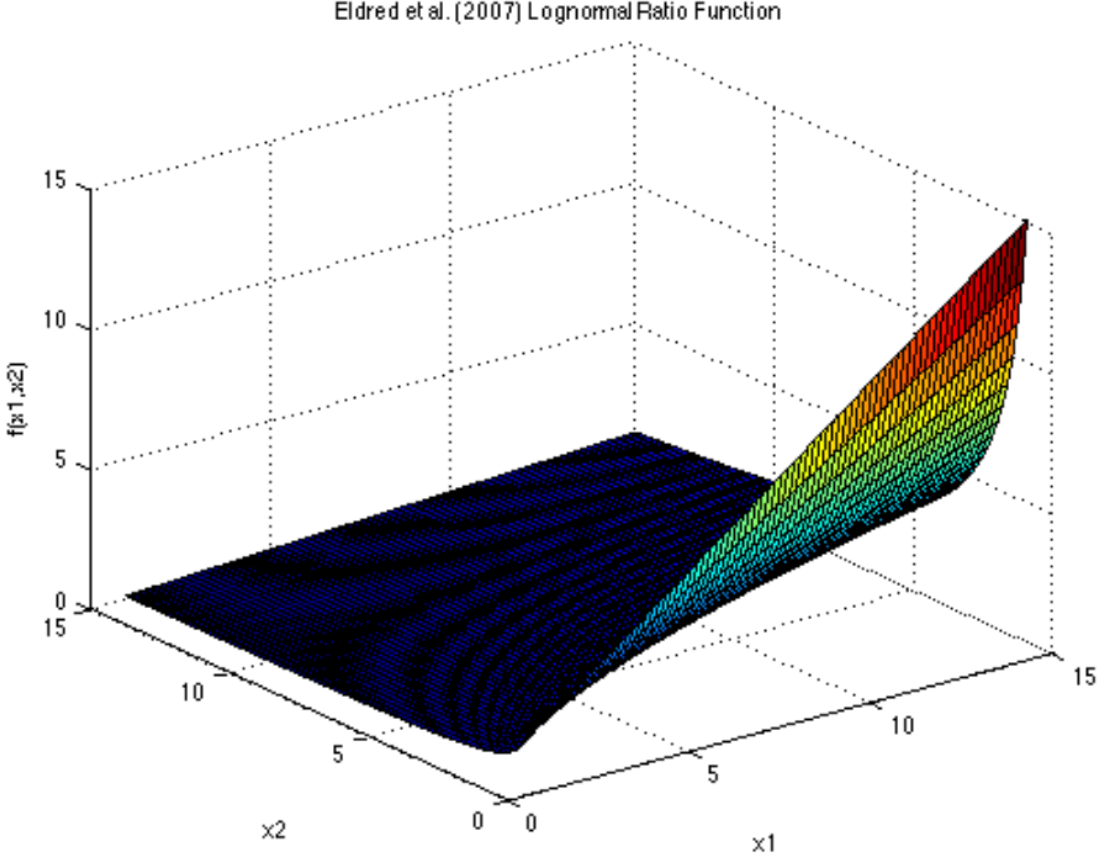
Code Blame 3440 lines (2535 loc)

```
1  #!/usr/bin/env python3
2
3  import numpy as np
4  from pytuq.func.func import Function
5
6  # TODO: add complete support for 1-d functions
7
8  # https://infinity77.net/global_optimization/test_functions_2d.html
9  # 1-d functions
10
11 class SineSum(Function):
12     """
13     Problem 02 [https://infinity77.net/global_optimization/test_functions_2d.html#f02]
14     """
15     def __init__(self, c1=1., c2=1.):
16         super().__init__()
17         self.name = name
18         self.c1, self.c2 = c1, c2
19         self.dim = 1
20         self.outdim = 1
21
22         self.setDimDom(domain=[-10, 10], range=[-1, 1])
23
24     def __call__(self, x):
25         r"""Simple sum of sine functions"""
26
27         .. math::
28             f(x) = \sin(c_1 x) + \sin(c_2 x)
29
30
31         Default constant value: 0
32
33         Args:
34             x (np.ndarray): Input array of size (N,1)
35
36         Returns:
37             np.ndarray: Output array of size (N,1)
38         """
39         return np.sin(self.c1 * x) + np.sin(self.c2 * x)
40
41     def grad(self, x):
```

Test Functions and Datasets

Uncertainty Quantification Test Problems

ELDRED ET AL. (2007) LOGNORMAL RATIO FUNCTION



$$f(\mathbf{x}) = \frac{x_1}{x_2}$$

Description:

Dimensions: 2

This test example is a limit state function, defining the boundary between safe and failed region domain (Eldred et al., 2070).

Input Distributions:

The distributions of the input random variables are: $x_i \sim \text{Lognormal}(1, 0.5)$, for all $i = 1, 2$. There

Ackley(),

Adjiman(),

Alpine01(),

Alpine02(),

AMGM(),

BartelsConn(),

Bird(),

Bohachevsky(),

Branin01(),

Branin02(),

Brent(),

Bukin02(),

Bukin04(),

Bukin6(),

CarromTable(),

Chichinadze(),

Cigar(),

Colville(),

CosineMixture(),

Damavandi(),

DeckkersAarts(),

Dolan(),

EggCrate(),

ElAttarVidyasagarDutta(),

FreudensteinRoth(),

GoldsteinPrice(),

HimmelBlau(),

Hosaki(),

Keane(), X

Leon(),

Levy13(),

Matyas(),

McCormick(),

MieleCantrell(), X

Mishra03(), X

Mishra04(), X

Mishra05(),

Mishra06(),

Mishra08(), X

NewFunction03(),

N-D test functions, alphabe

Parsopoulos(),

Powell(),

Price01(),

Price02(),

Price03(),

Price04(),

Quadratic(),

RosenbrockModified(),

RotatedEllipse01(),

RotatedEllipse02(),

Schaffer01(),

Schaffer02(),

Schaffer04(),

SchmidtVetters(), X

Schwefel36(),

SixHumpCamel(),

ThreeHumpCamel(),

Treccani(),

Trefethen(),

Ursem01(),

Ursem03(),

Ursem04(), X

UrsemWaves(),

VenterSobieszczzanskiSobie

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Griewank(),

Trig

ChengSandu(),

SineId(),

Forrester(),

Friedman(),

GramacyLee(),

GramacyLee2(),



rv

Random variable package

mrsv.py

pcrv.py

rosen.py

- Parent random variable class
- Multivariate random variables
- **PCRV**, GMM, MVN, MCMCRV
- Sample, evaluate pdf, cdf
- Operations on random variables: mixture, inverse
-
- Rosenblatt transformation



fit

General fitting package (supervised ML)



fit.py

gp.py

- Parent fit class
- Gaussian process construction
- See *ex_gp.py*



gsa

Global sensitivity analysis package



gsa.py

- Parent gsa class
- Regression-based Sobol
- PC Sobol
- MOAT
- See *ex_gsa*.py*



Linear regression package

lreg.py

anl.py

opt.py

bcs.py

merr.py

- Parent linear regression class
(derives from *fit* class)
- Given basis evaluator, or an A-matrix
- *anl* includes variational inference
- *fit()*, *predict()* similar to Scikit-learn
- *predict()* produces prediction (co)variance, too
- See *ex_lreg*.py*



linred

Linear dimensionality reduction package

linred.py

svd.py

kle.py

klurr.py

klrr.py

- Parent linear dim. red. class
- Derived SVD and KLE classes
- KL+Surrogate capabilities
- Extensible to nonlinear?

Manifold? Autoencoders?



optim

Optimization package

optim.py

gd.py

- Parent class to allow derived optimization methods.
- Bare-bones gradient descent.
- See *ex_optim.py*
- Need to add a lot more.



minf

Model inference package

calib.py

infer.py

minf.py

mcmc.py

likelihoods.py

priors.py

- Parent calibration class, with a similar signature to optimization class
- Born out of embedded model error work
- Allows flexible PC embedding
- MCMC flavors: AMCMC, HMC, MALA
- See *ex_minf*.py* and *ex_mcmc*.py*



Utilities of all sort (no classes)

decors.py

funcbank.py

maps.py

metrics.py

stats.py

mindex.py

integr.py

plotting.py

uqtk_utils.py

xutils.py

- These are common utilities used across the library
- Some shared between PyTUQ and QUiNN
- Some re-org needed



workflows

Workflows package (more to come)



fits.py

Module for multi-output fit tasks

uprop.py

Module for uncertainty propagation tasks



surrogates

Surrogate wrappers



nn.py

Wrapper class to QUiNN's NN surrogate

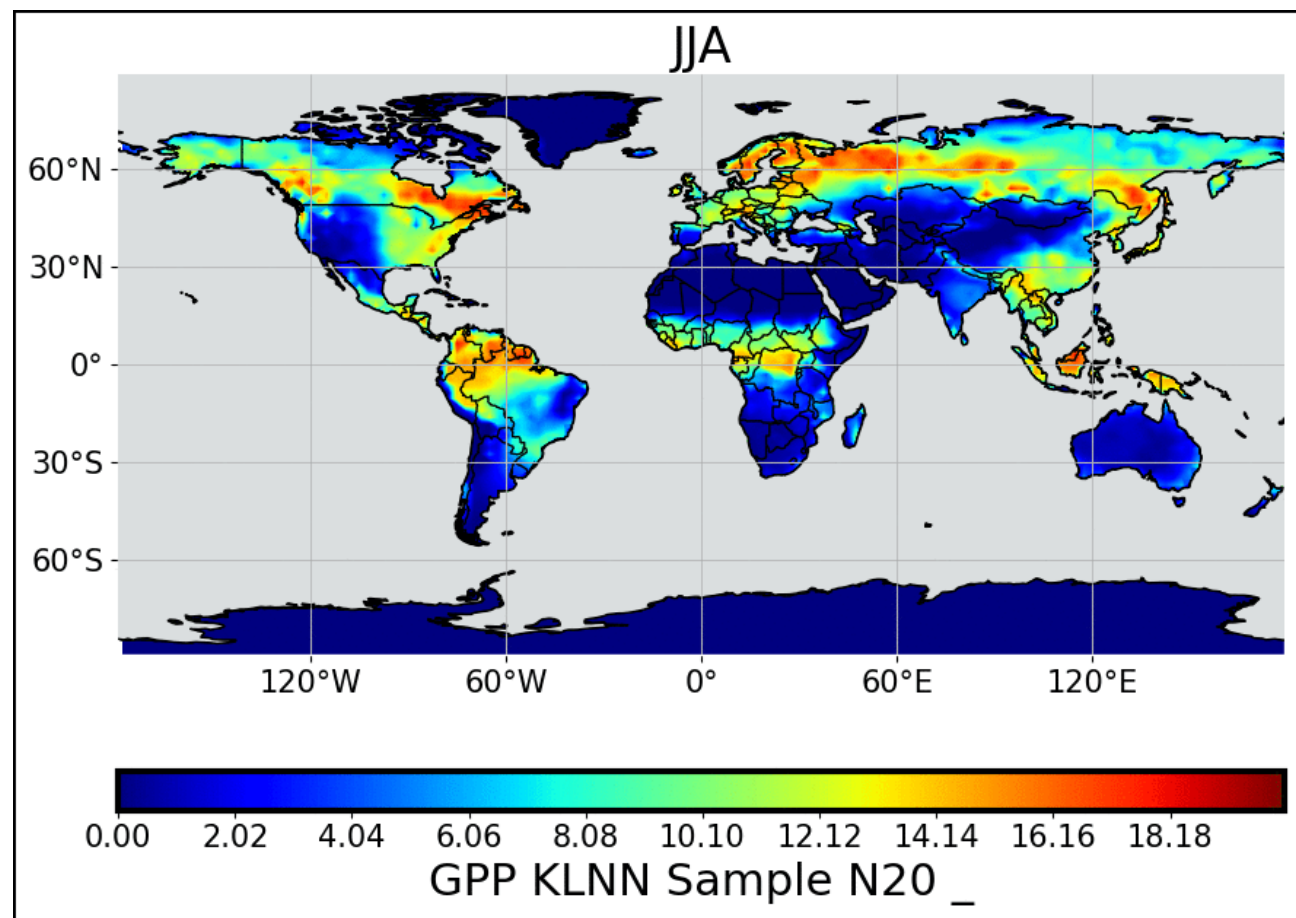
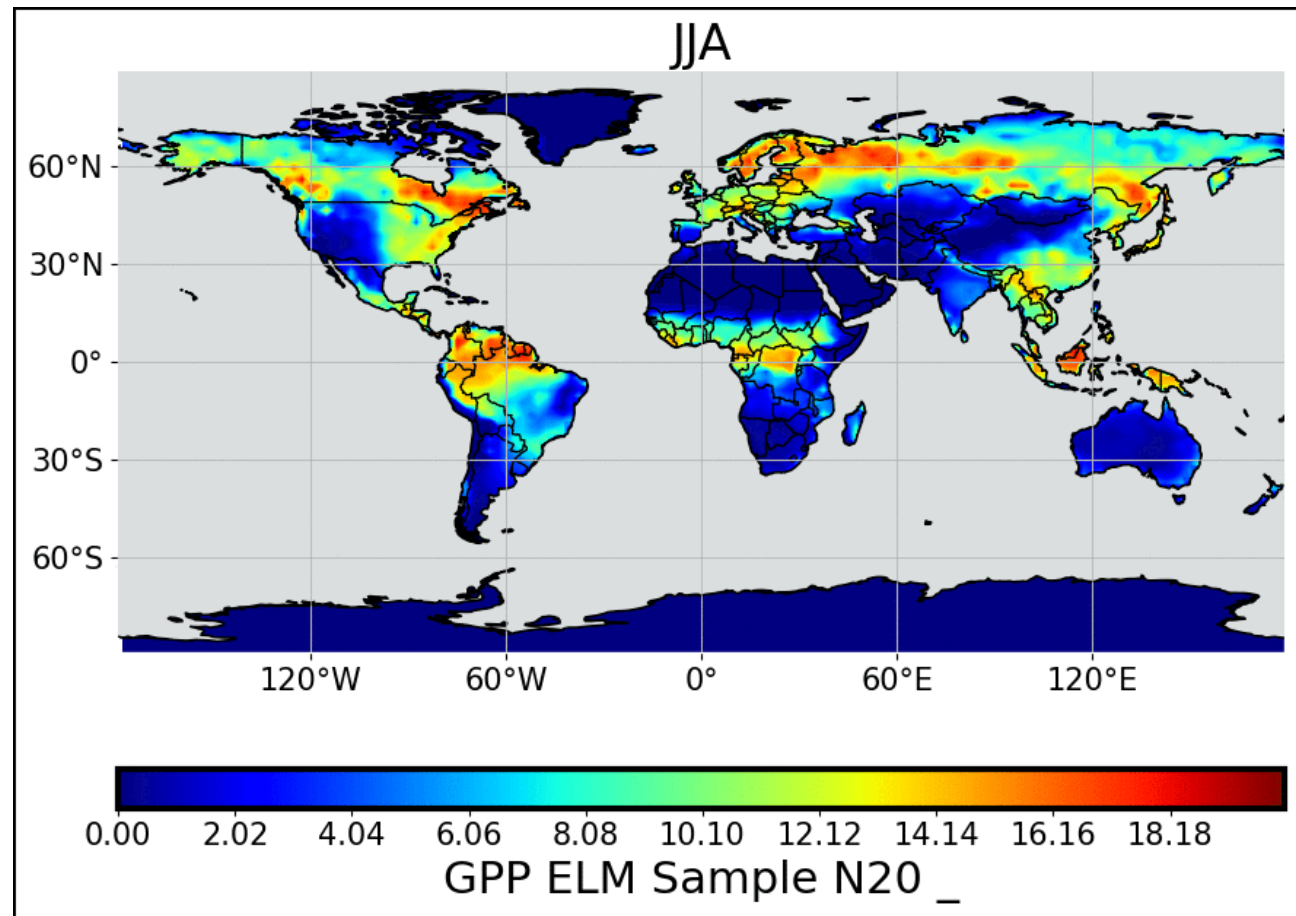
pce.py

Wrapper class to PyTUQ's PCE surrogate

Application Examples

Reduced dim. surrogate-enabled calibration

BER: E3SM Land Model UQ

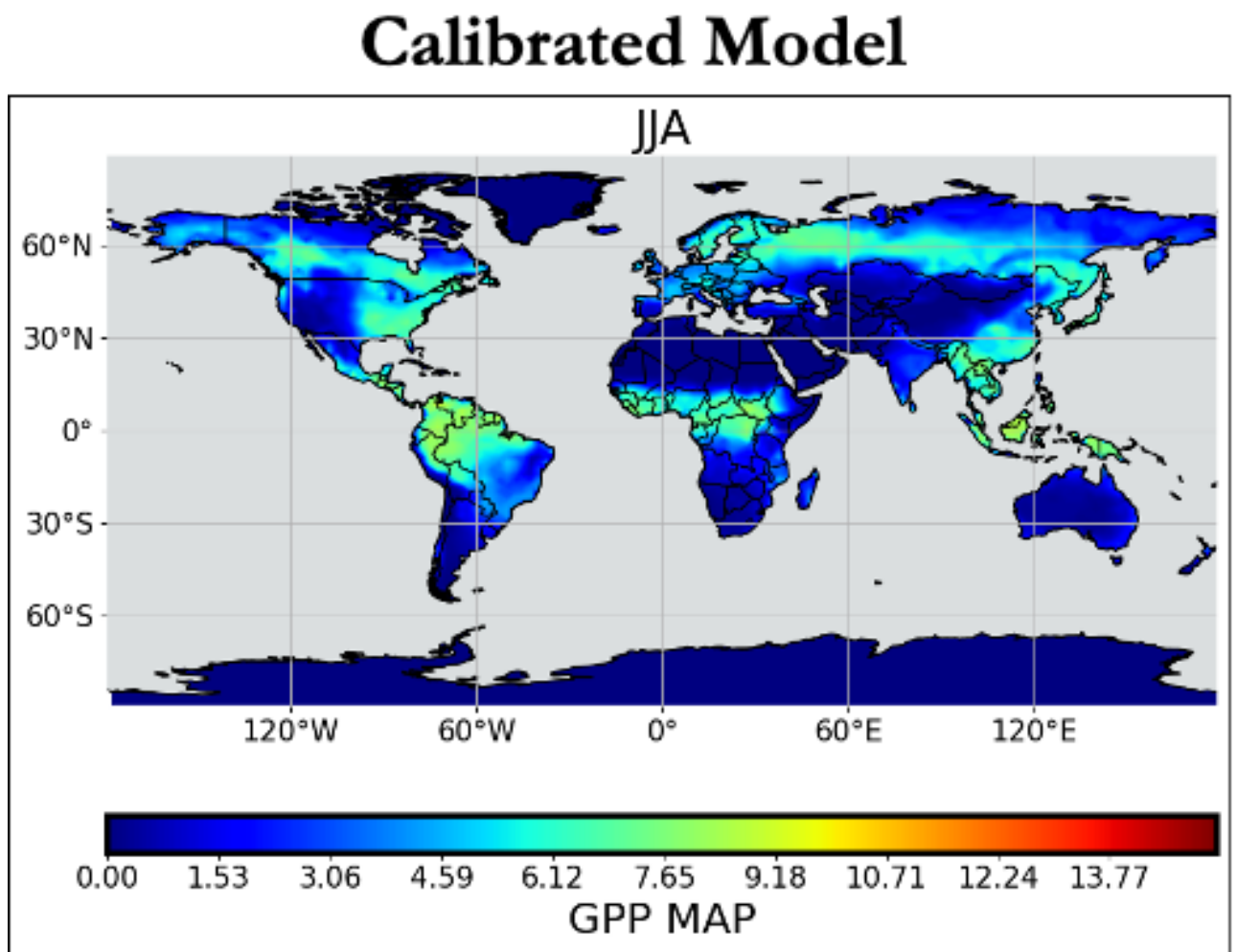
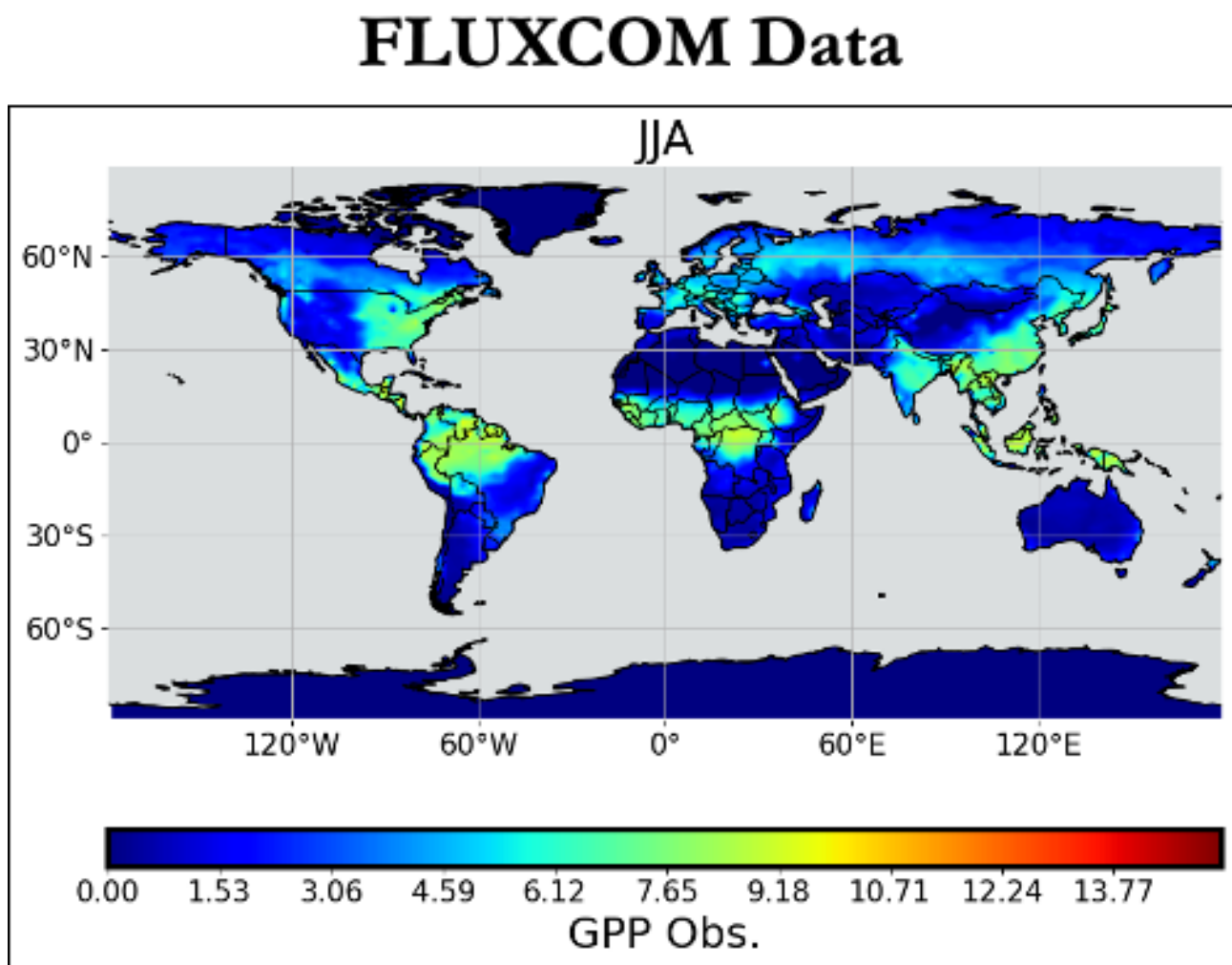
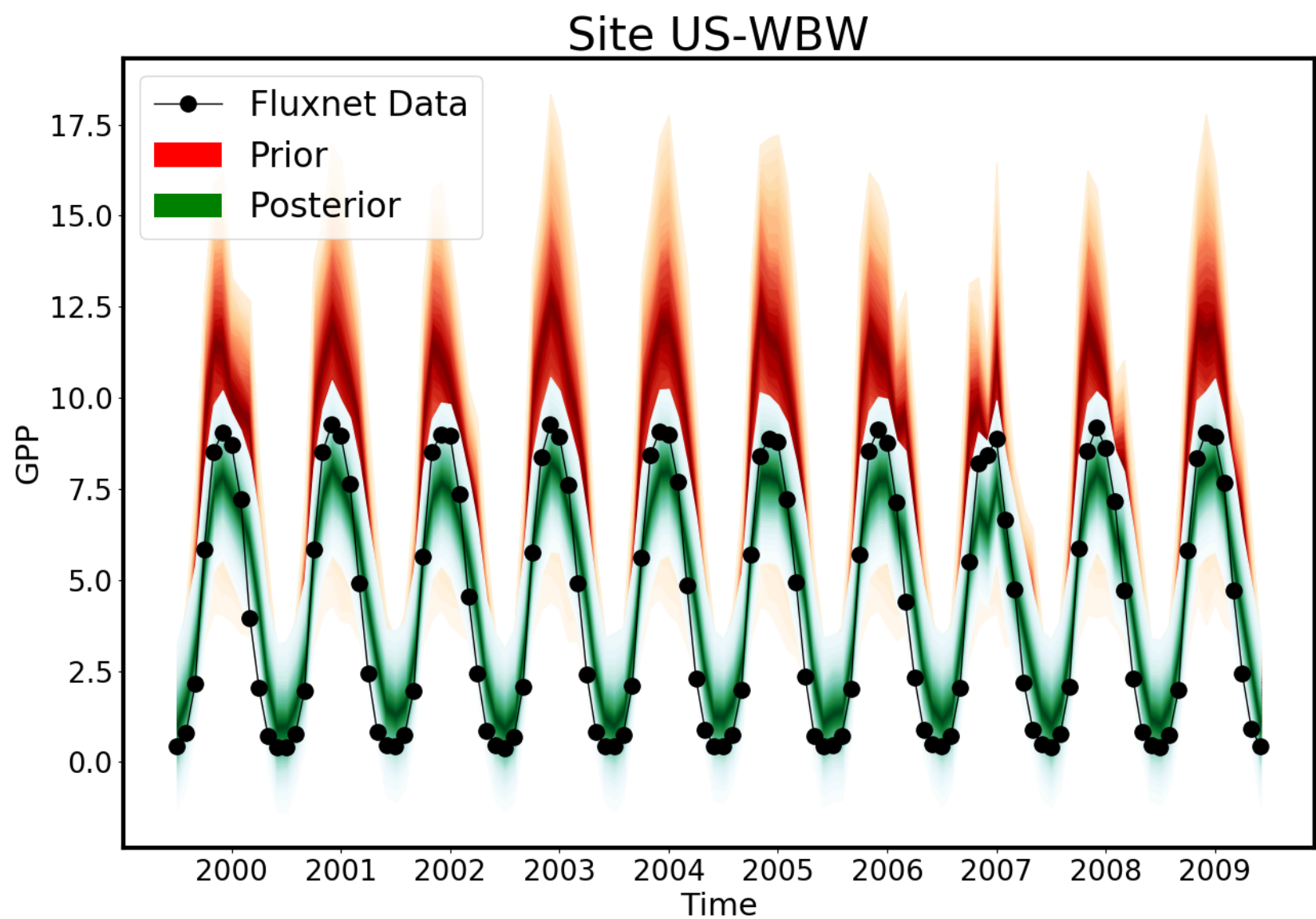


KL+NN spatiotemporal surrogate, 10 params



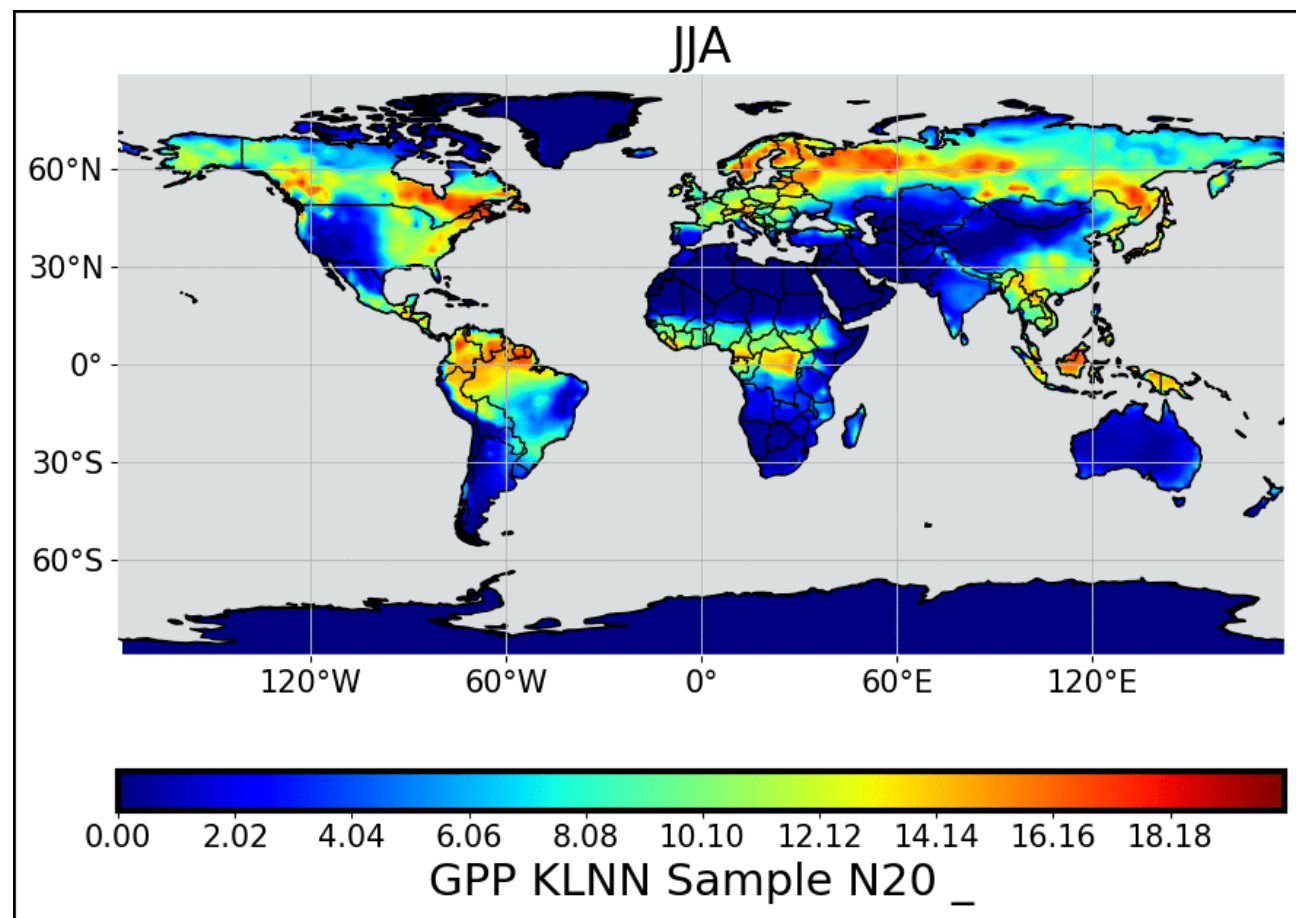
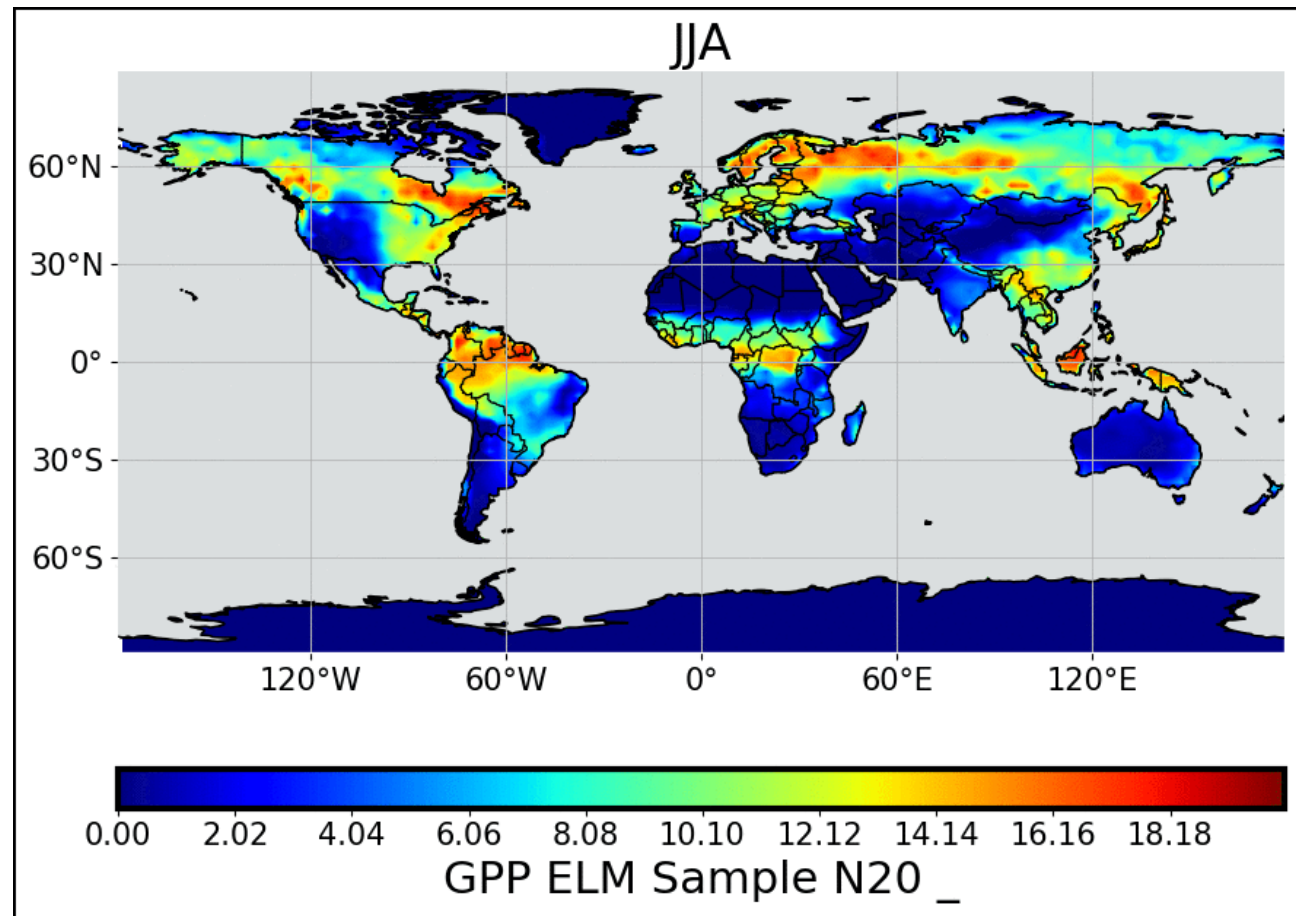
Spatial slice of calibrated model

Temporal slice of calibrated model



Reduced dim. surrogate-enabled calibration

BER: E3SM Land Model UQ

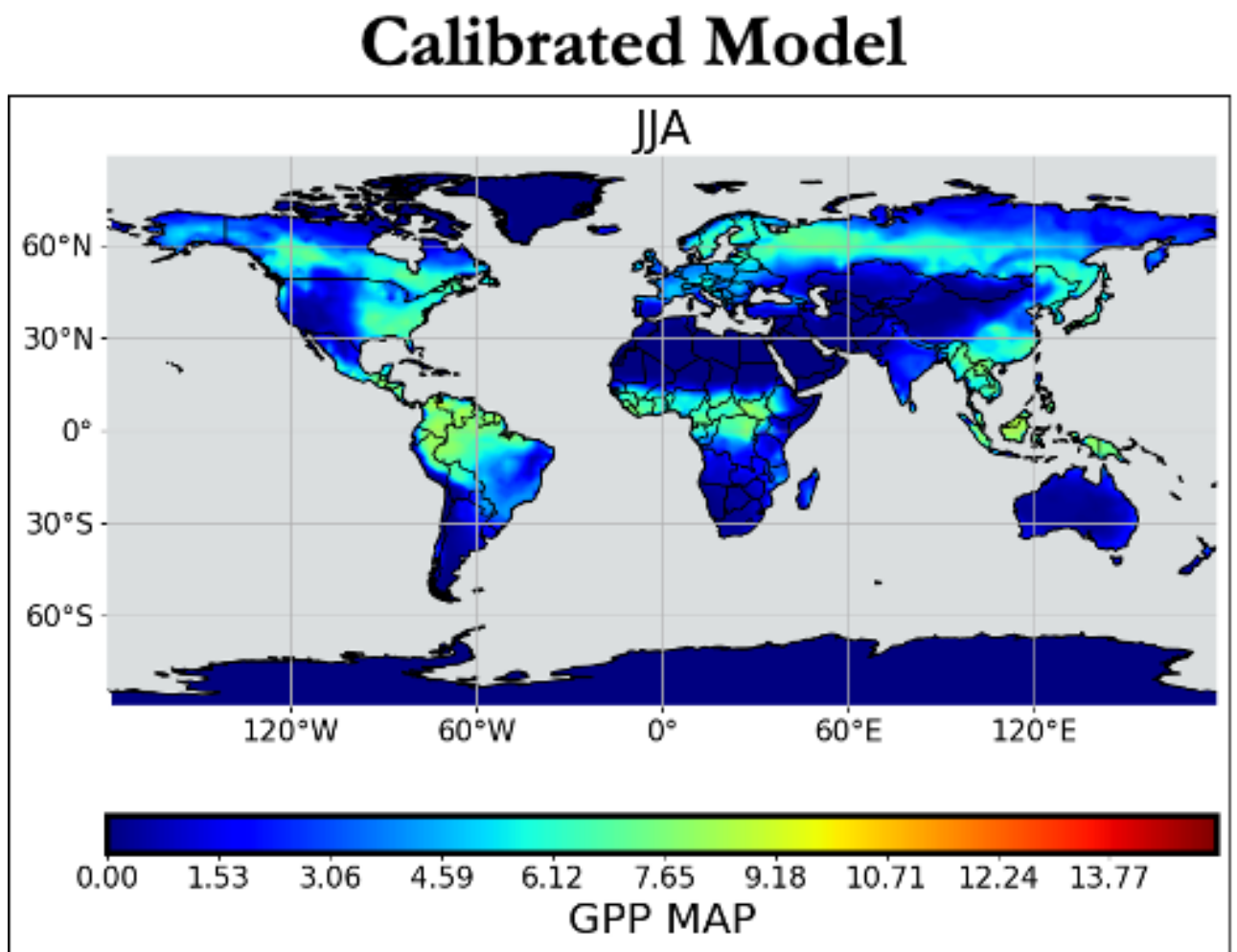
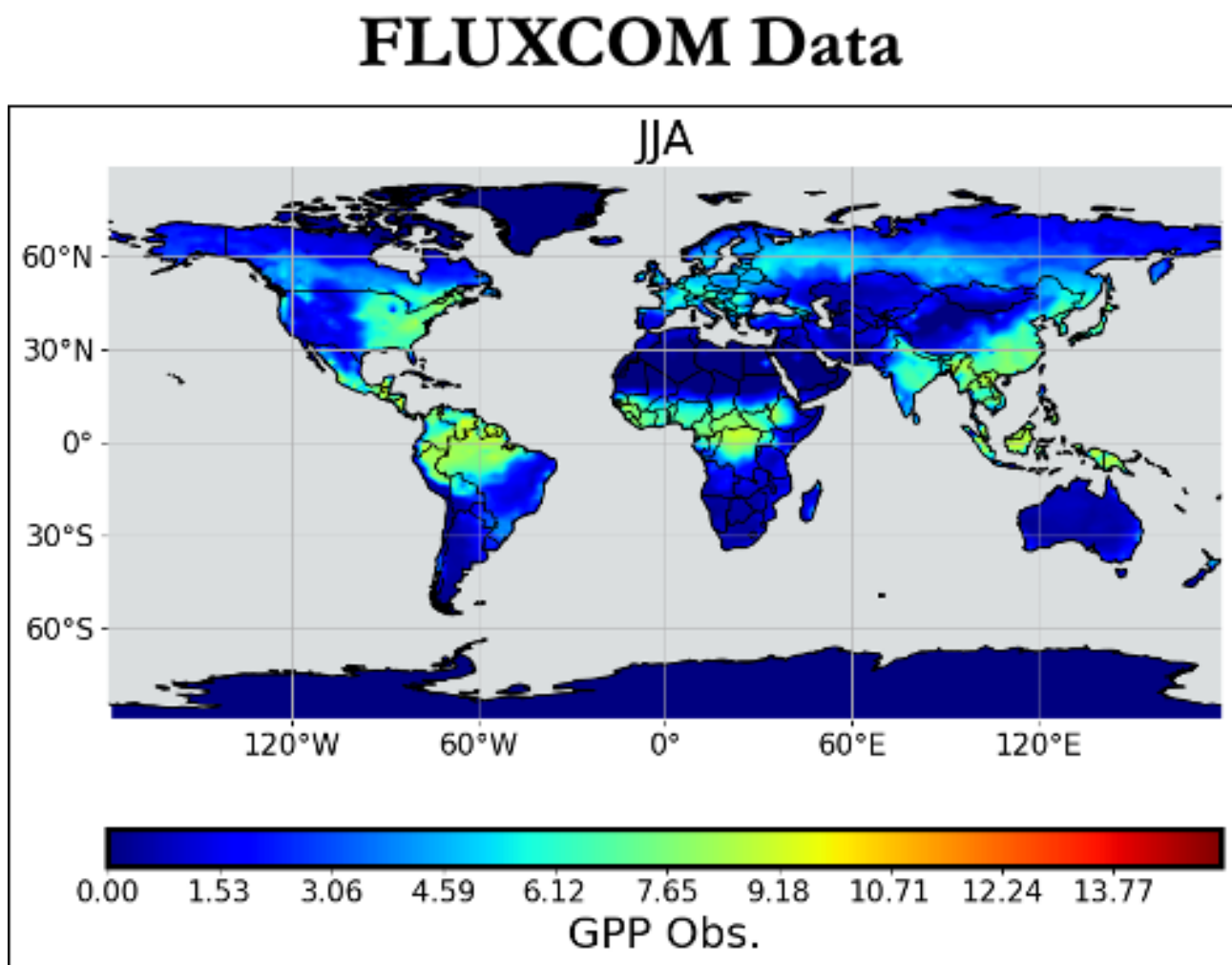
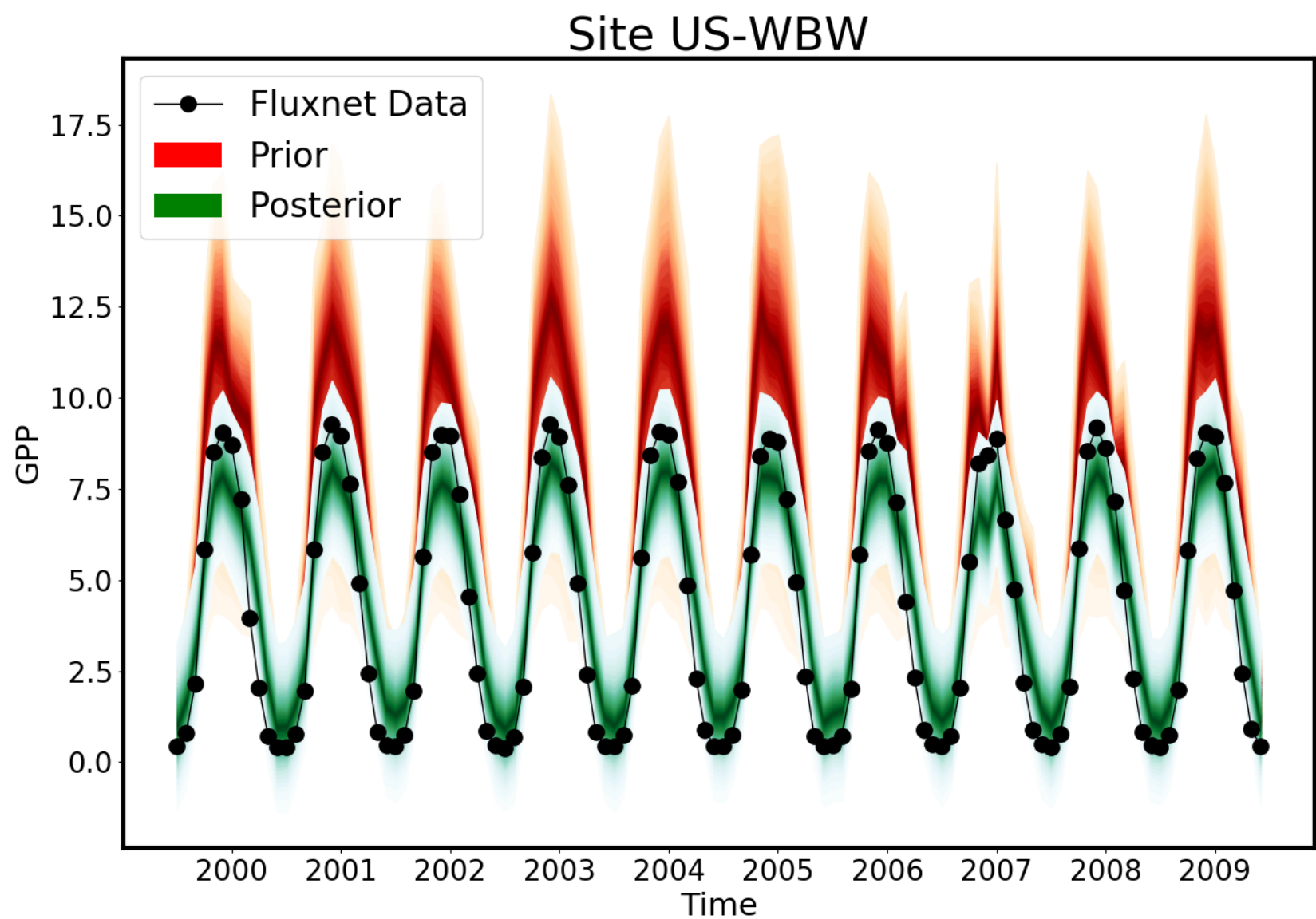


KL+NN spatiotemporal surrogate, 10 params



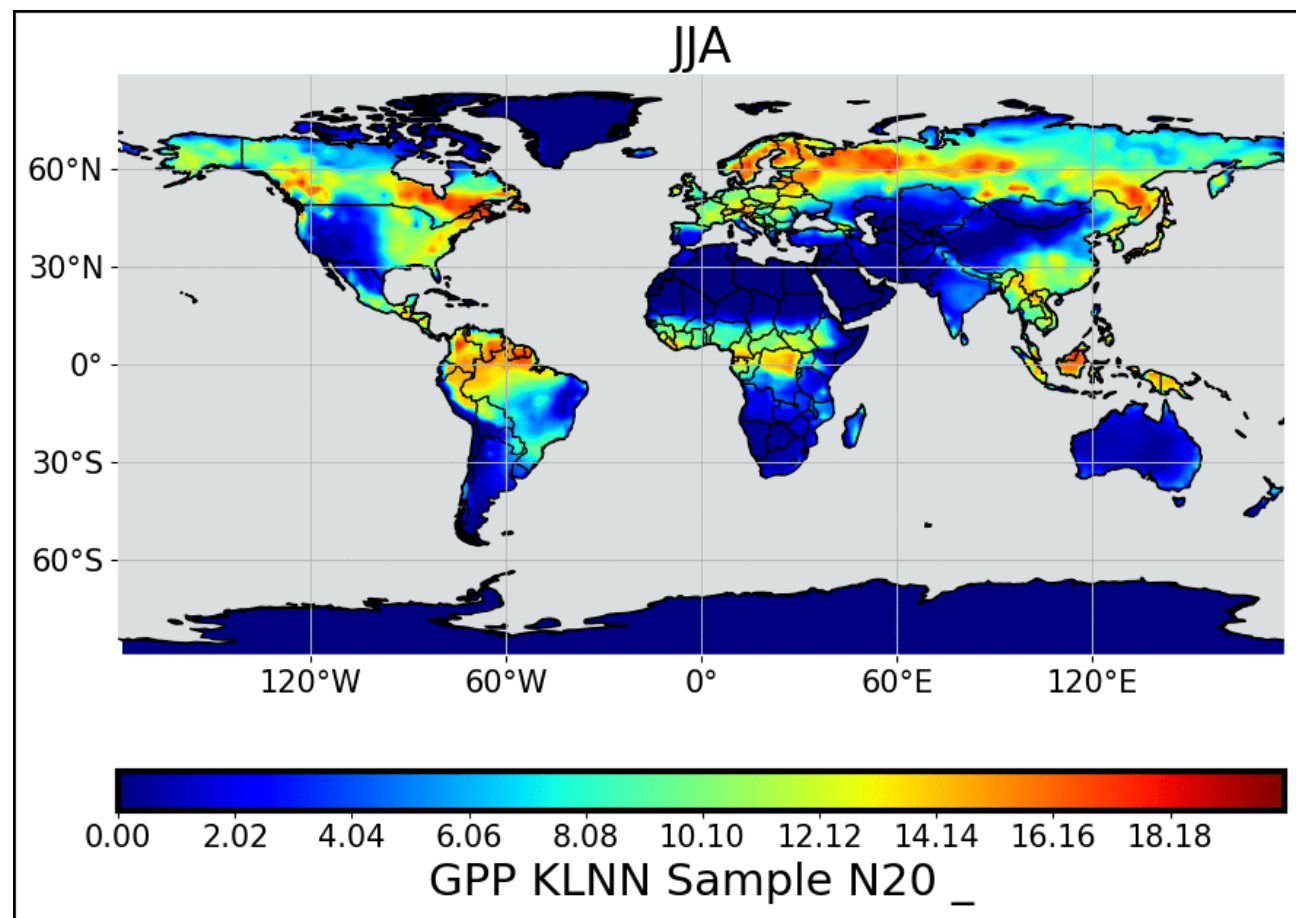
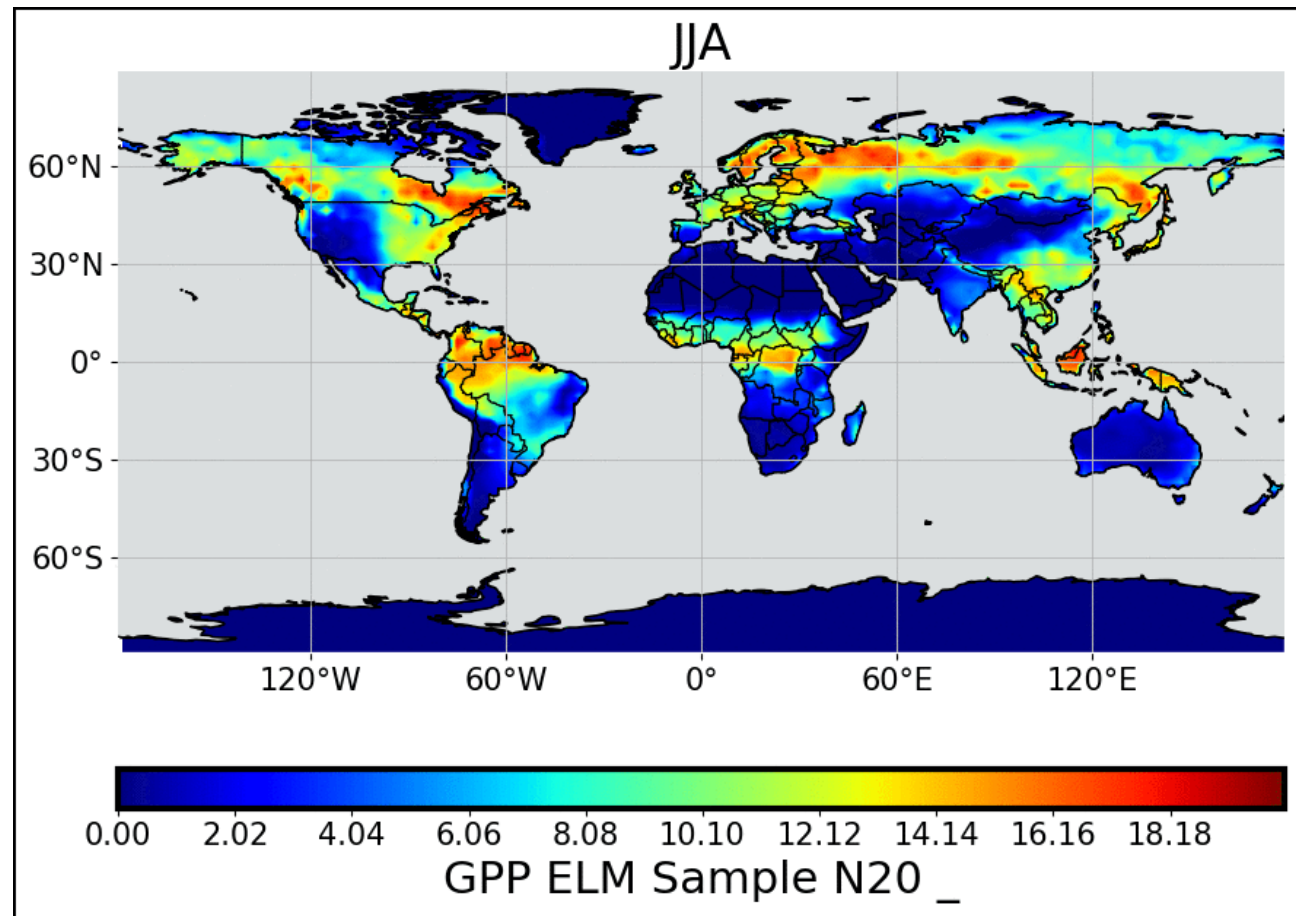
Spatial slice of calibrated model

Temporal slice of calibrated model




Reduced dim. surrogate-enabled calibration

BER: E3SM Land Model UQ

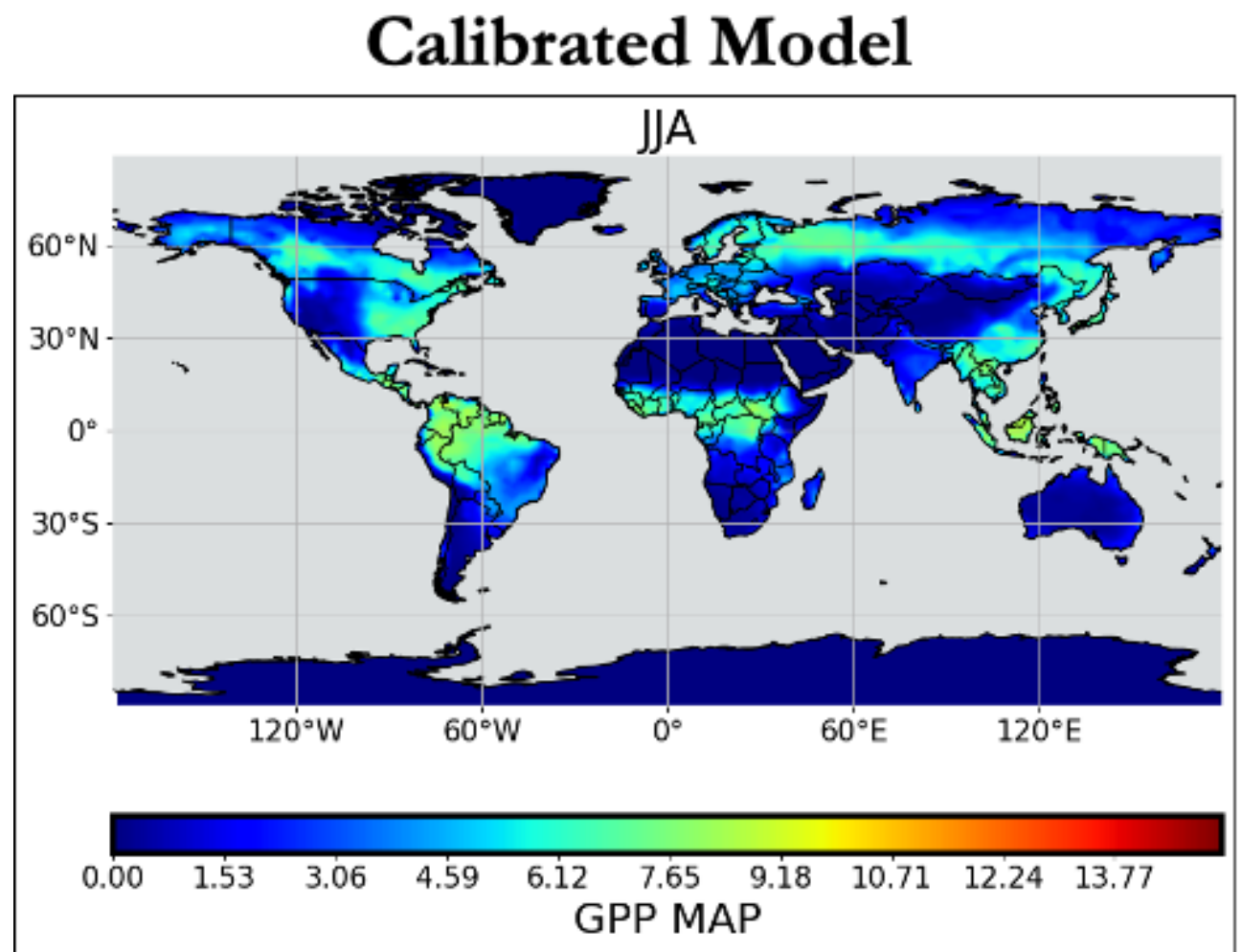
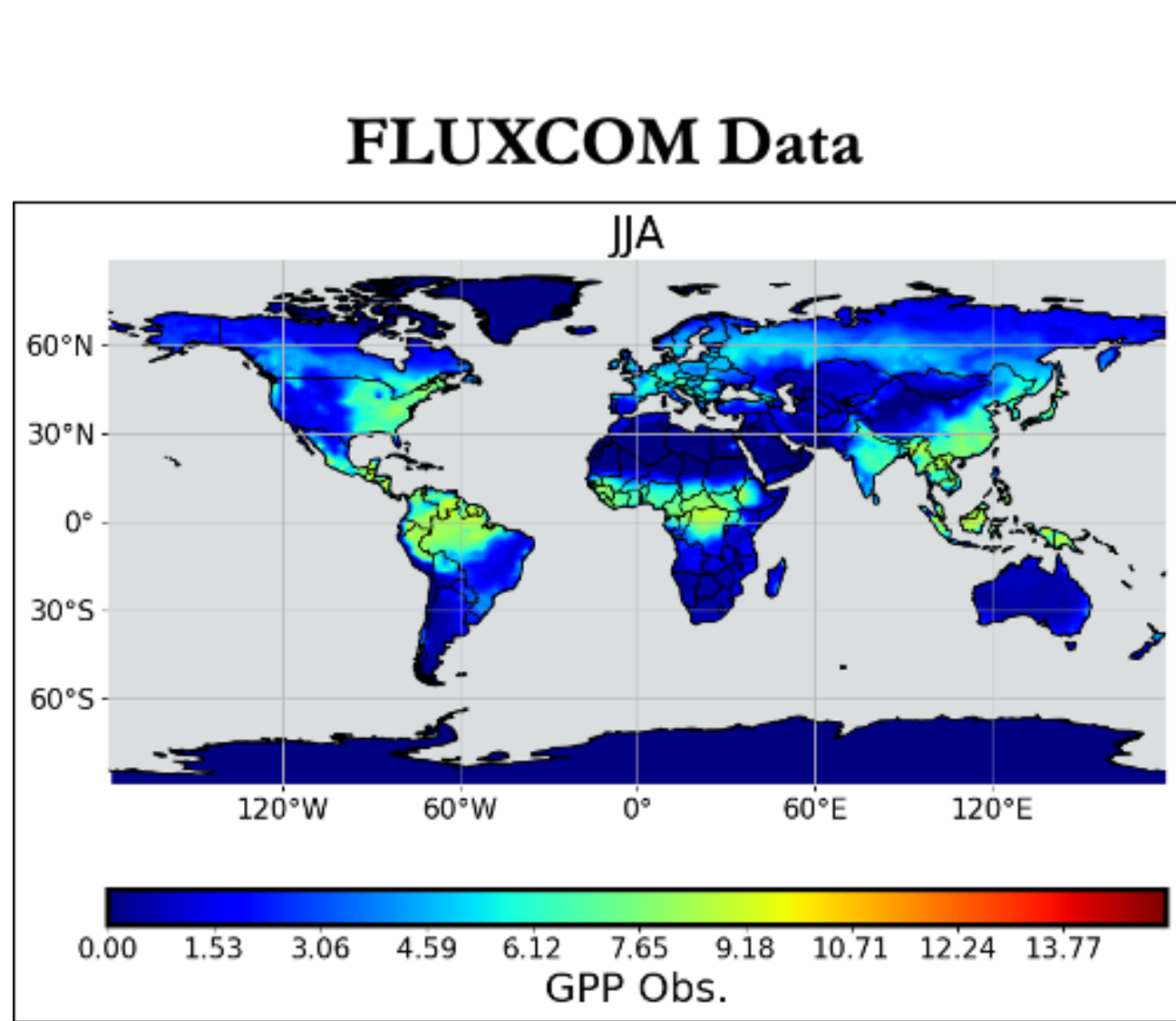
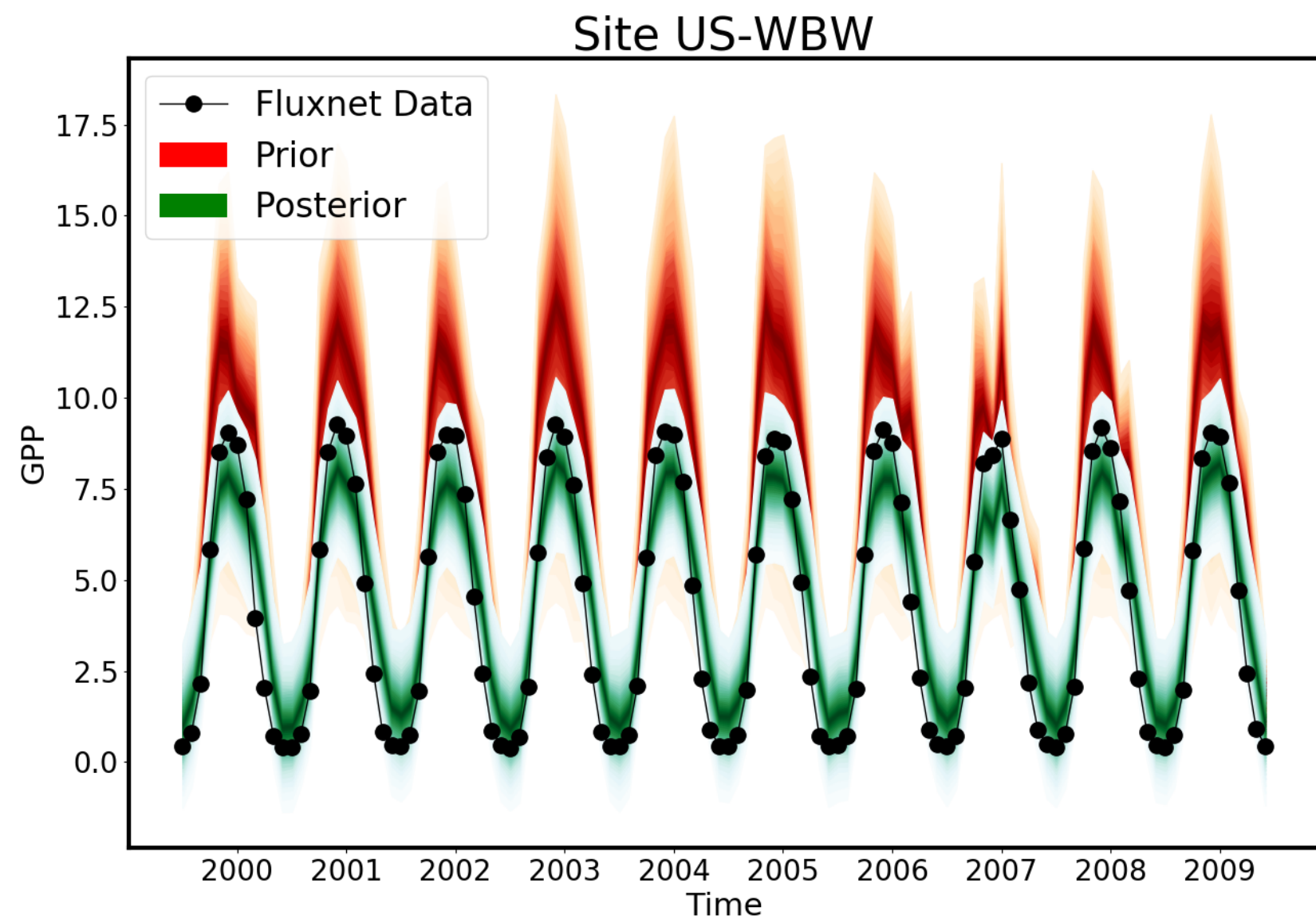


KL+NN spatiotemporal surrogate, 10 params



Spatial slice of calibrated model

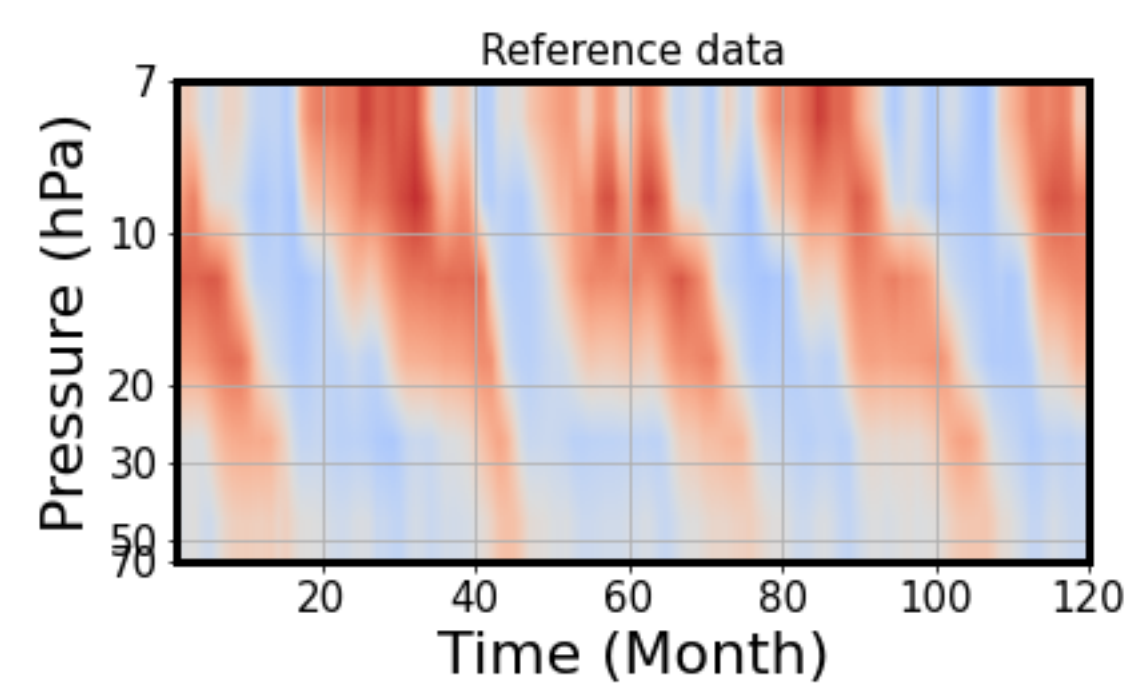
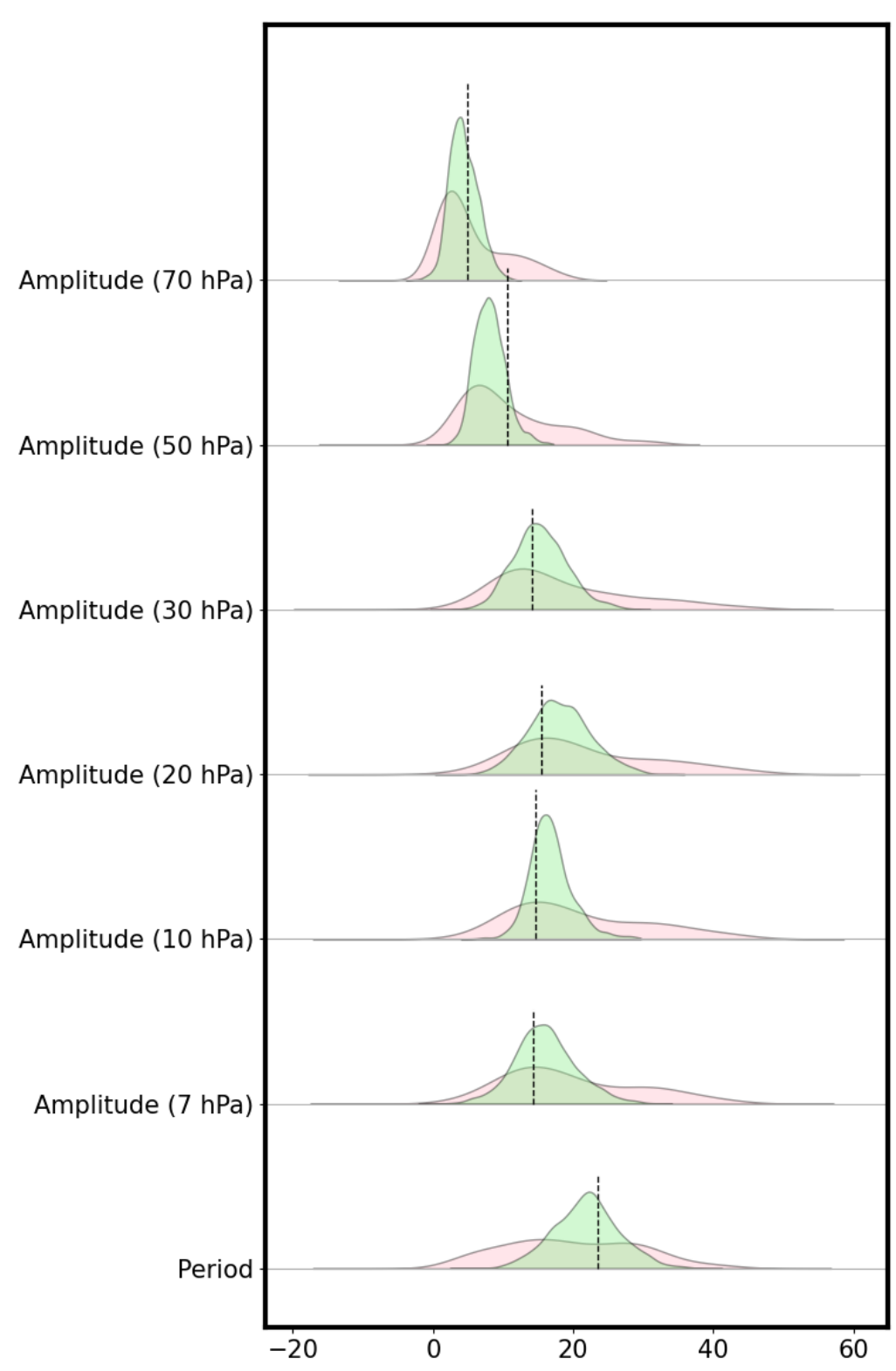
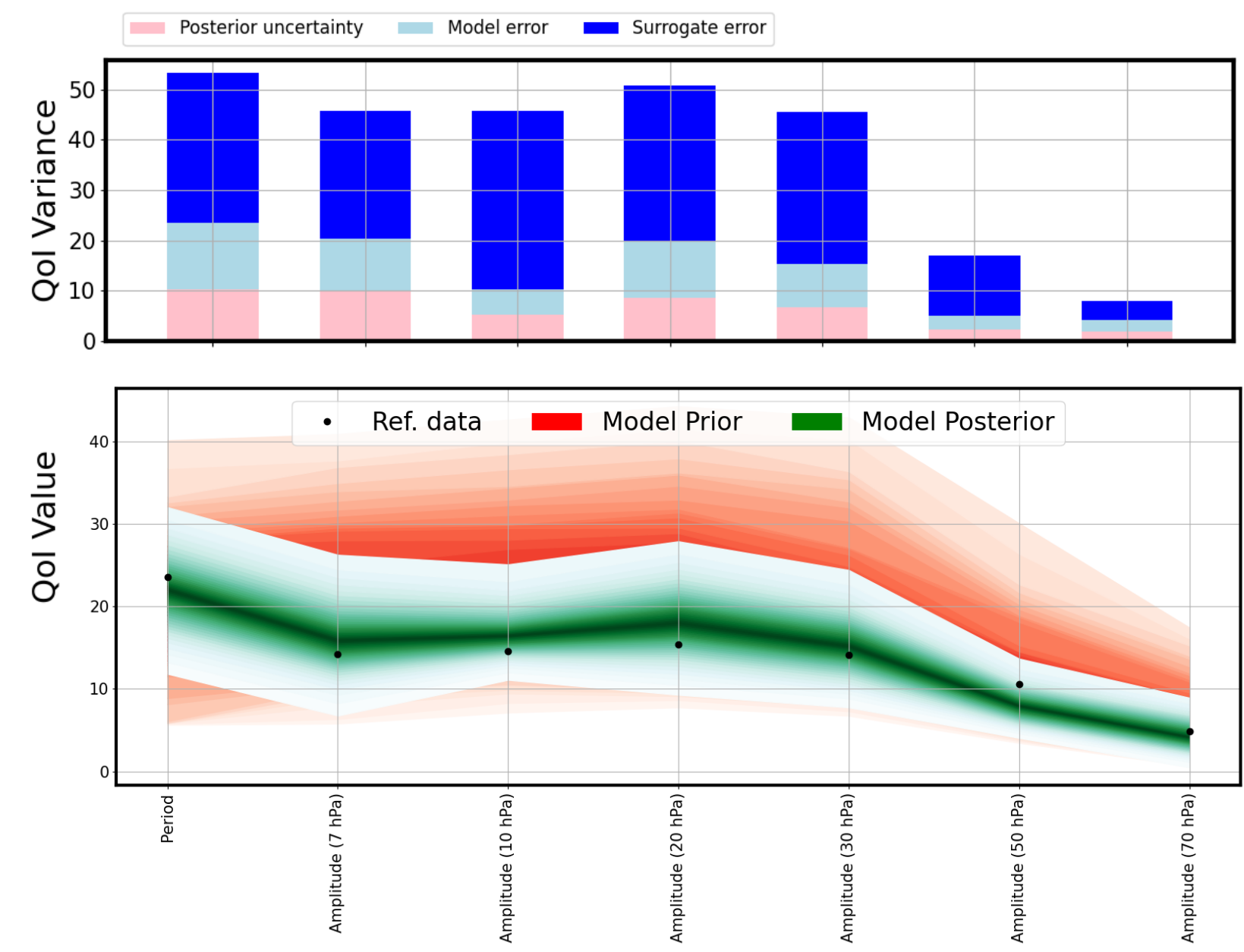
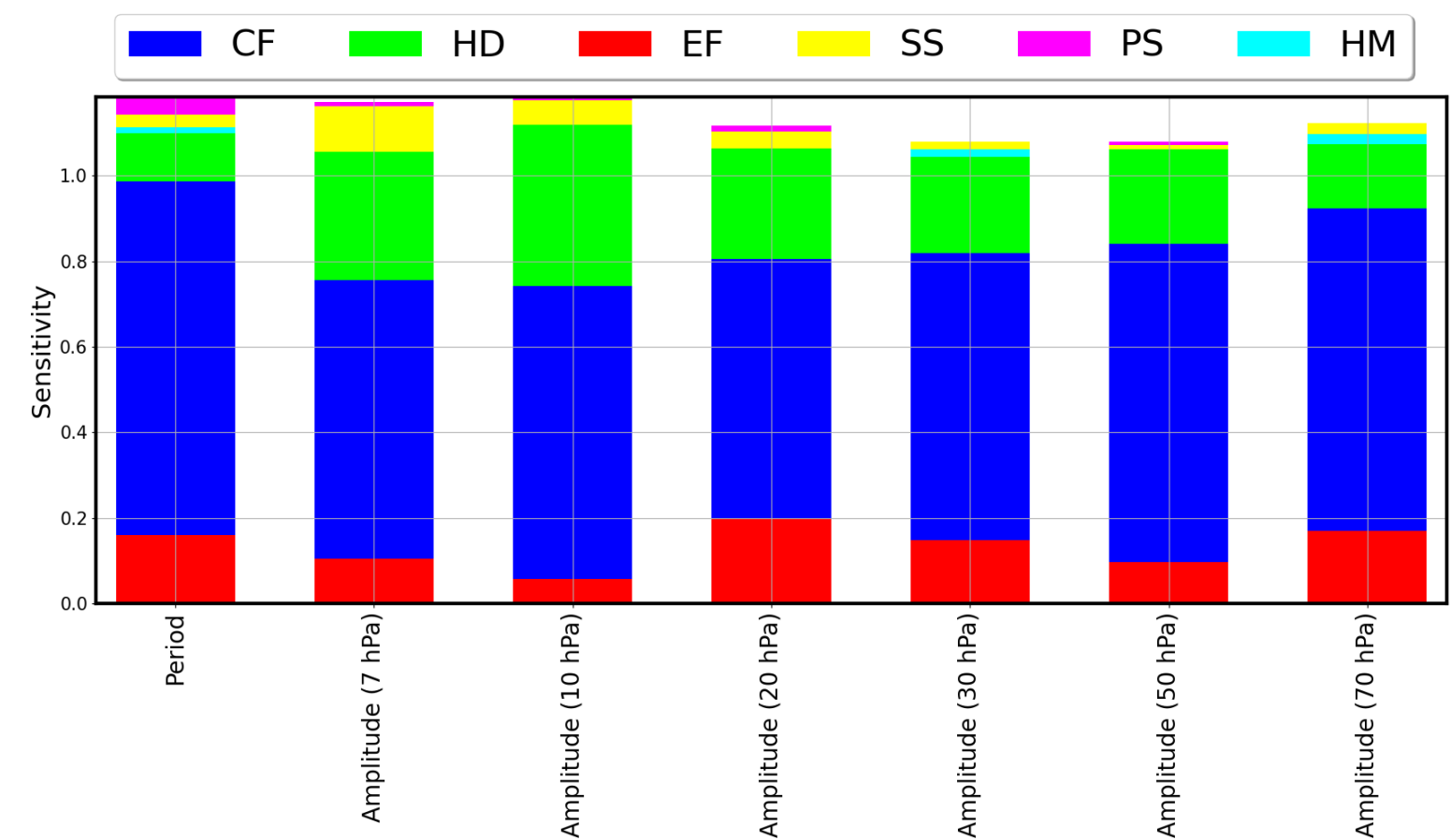
Temporal slice of calibrated model



6-param perturbed ensemble,
PC surrogate + GSA

Calibration with model error
and uncertainty attribution

Marginal posterior
predictives



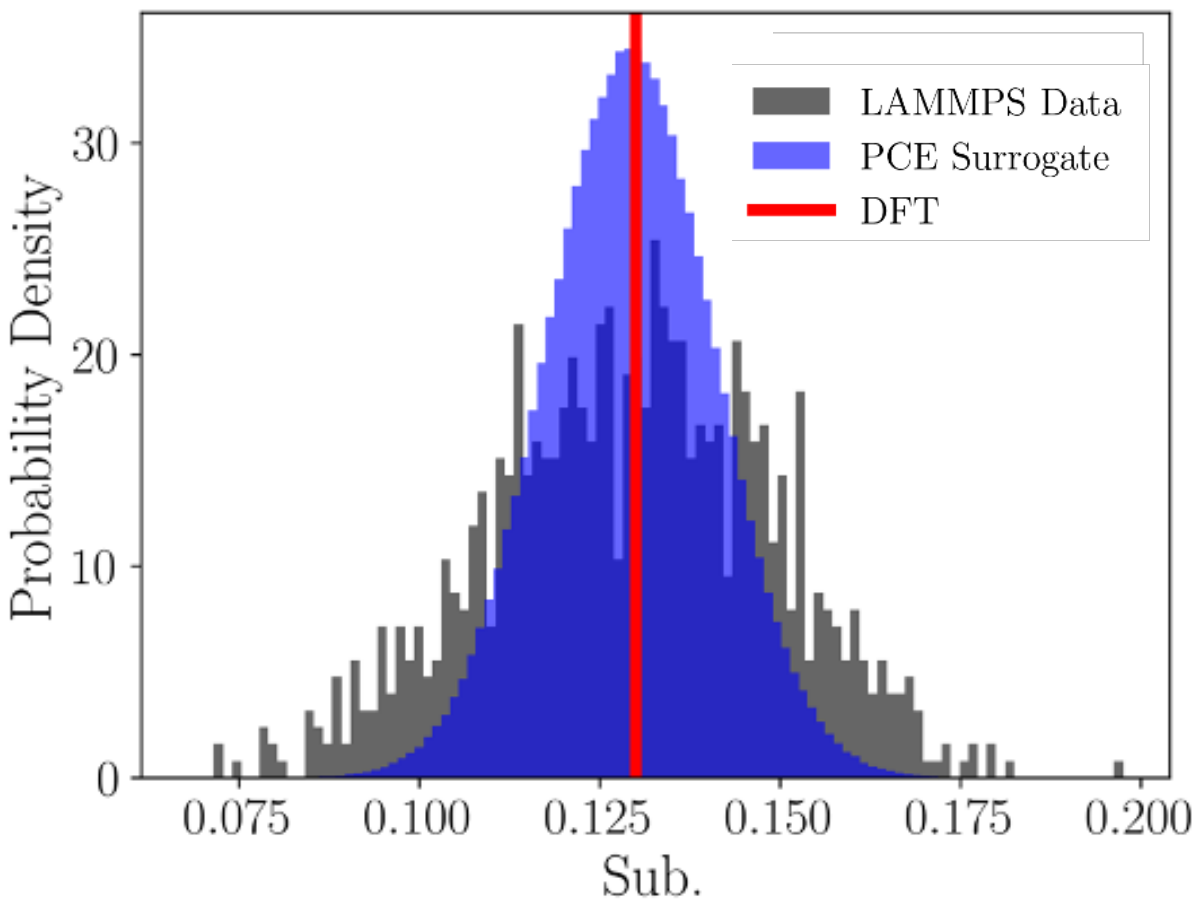
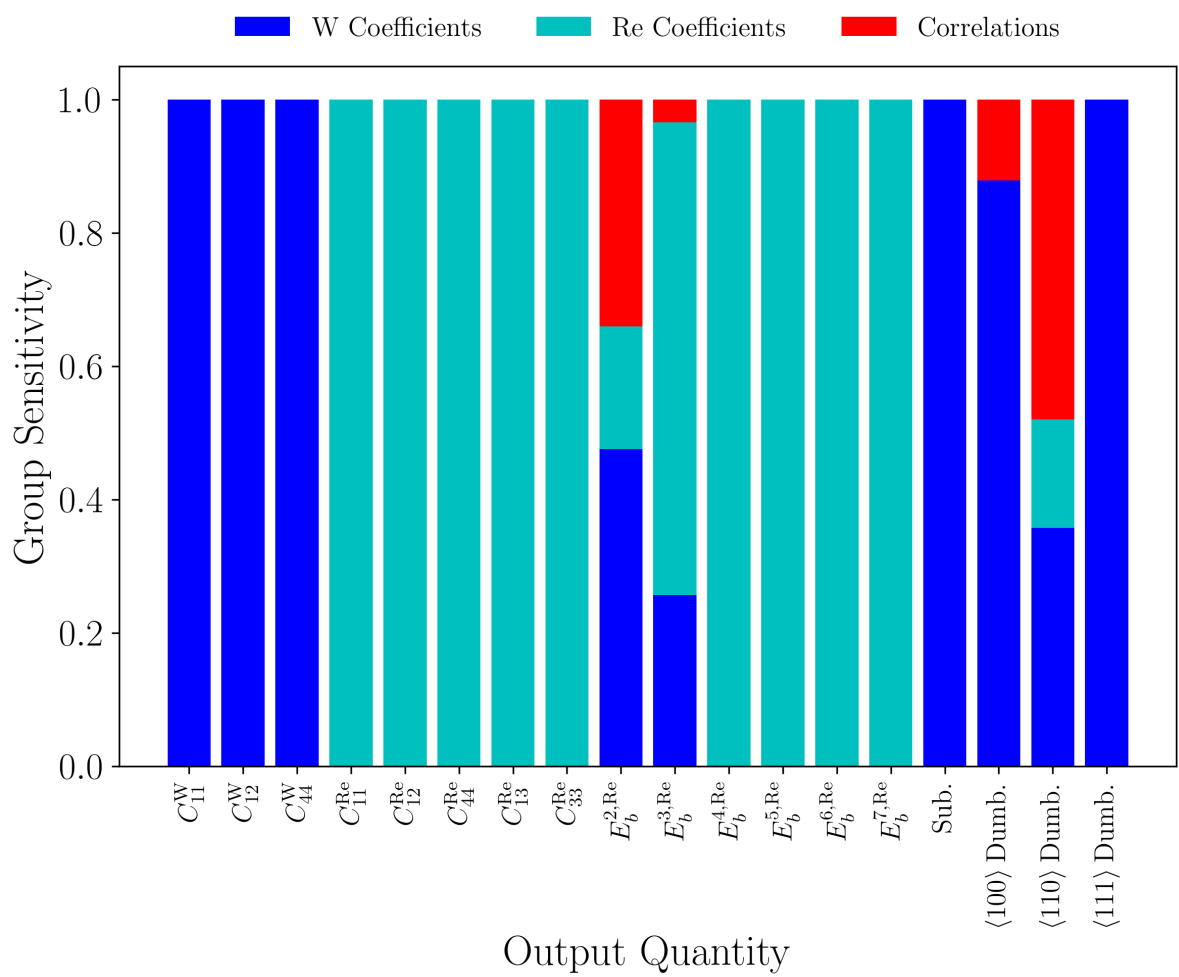
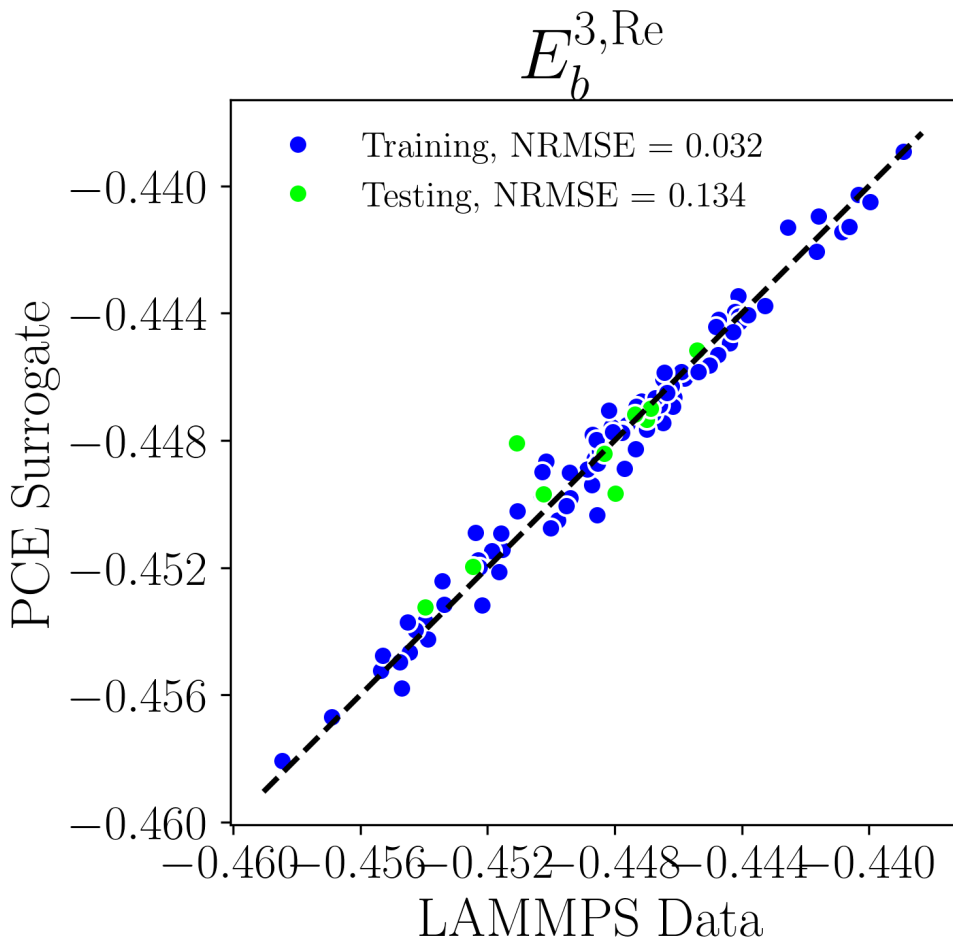
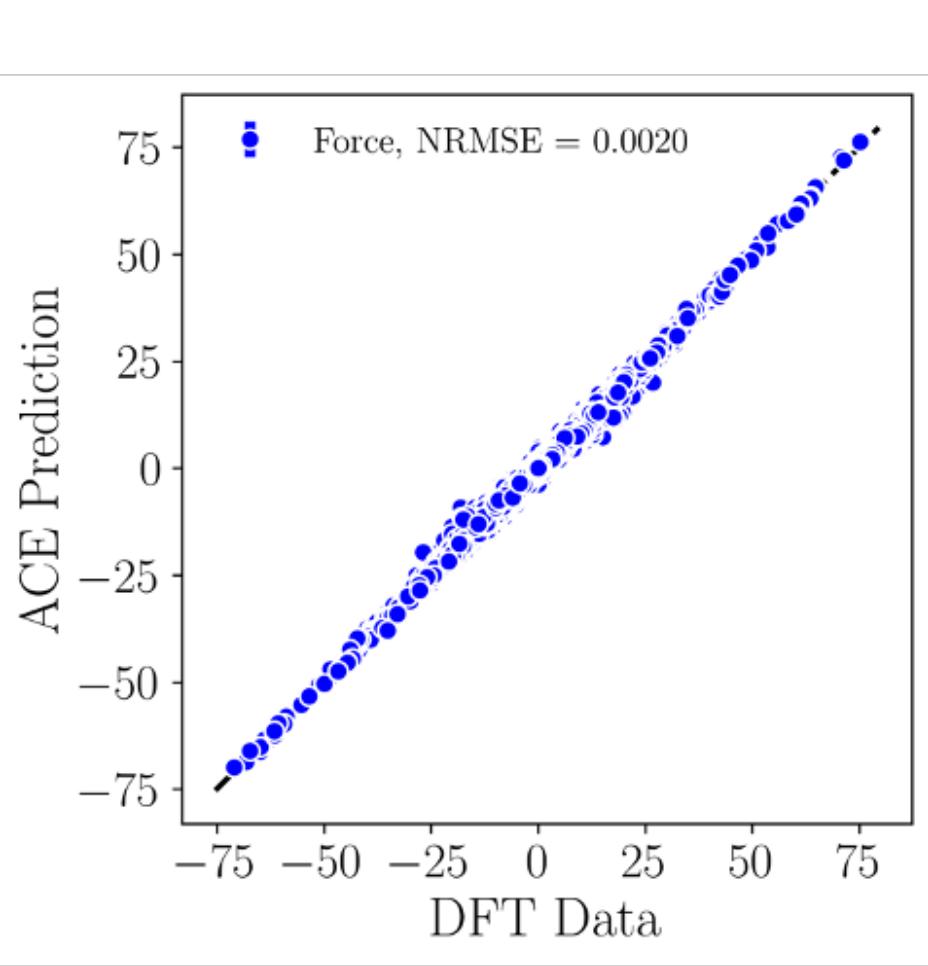
KL dimensionality reduction of
wind fields, KL+PC surrogate
to enable calibration

Bayesian linear regression (BLR) to fit, with UQ, interatomic potential to DFT data

PC-based propagation of uncertainty through MD Qols

GSA and uncertainty attribution

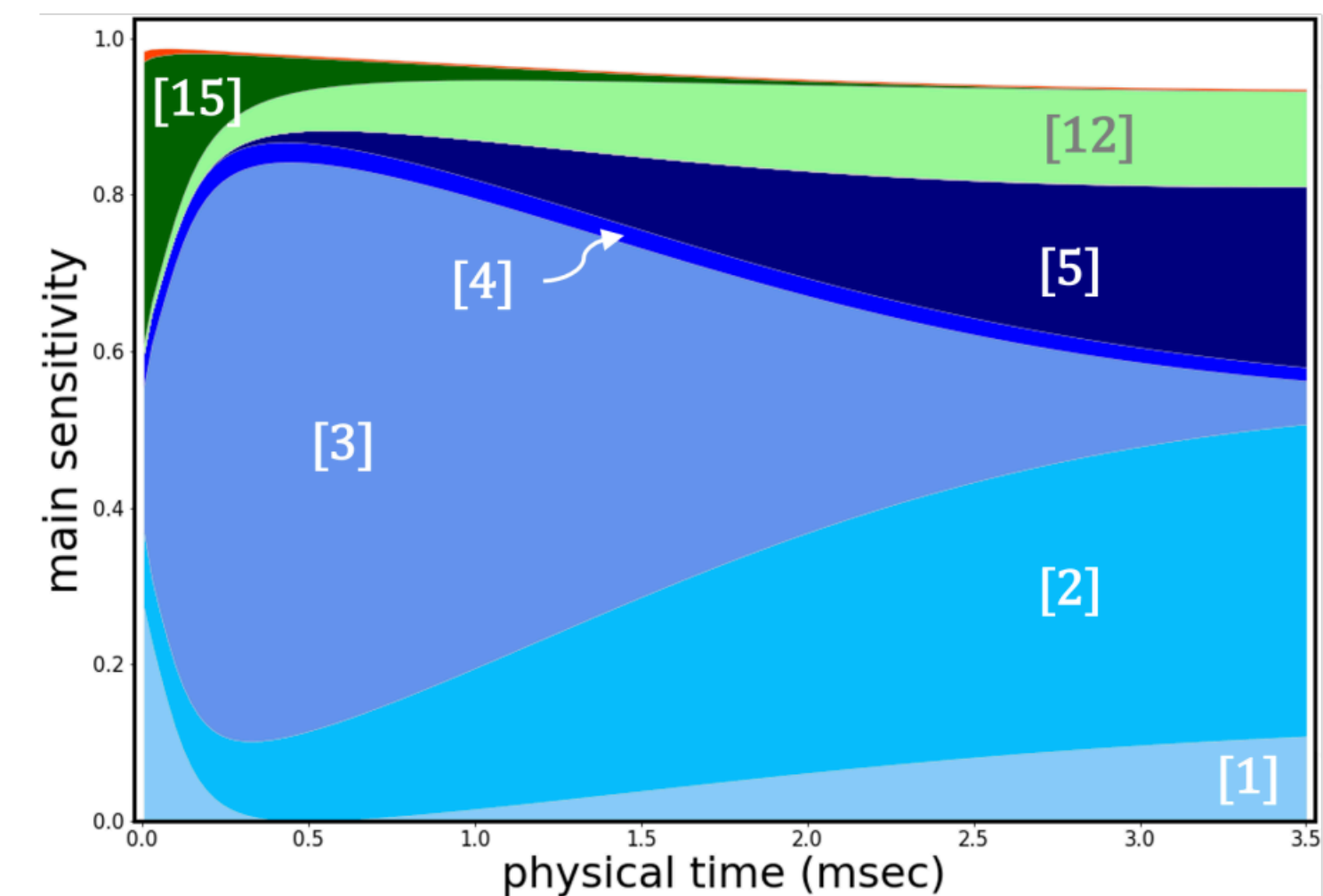
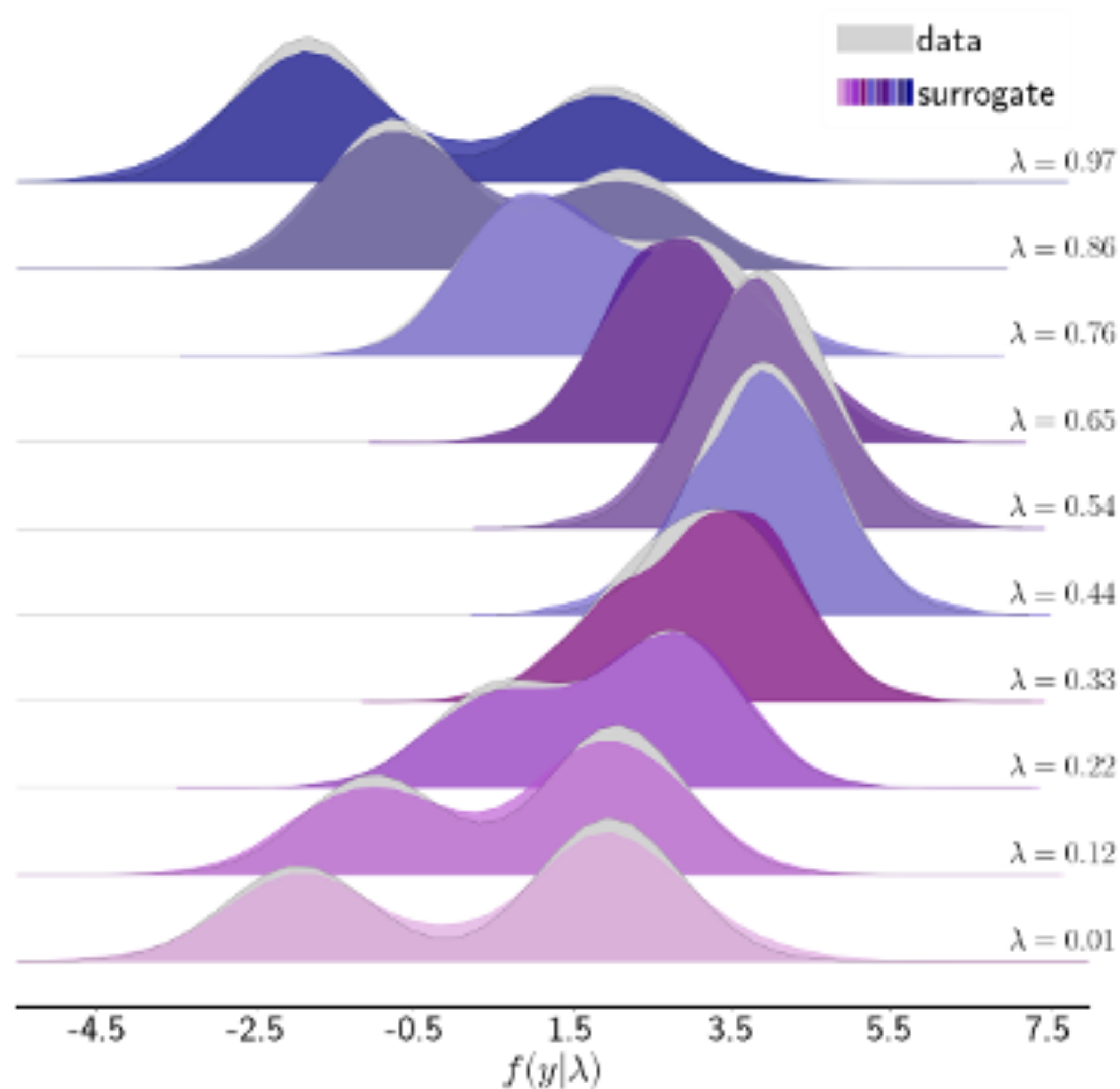
Validation with DFT data



Rosenblatt transformation merged with parametric fit to build a joint stochastic-parametric PC surrogate

Karhunen-Loève expansion to extend it to random fields

Global sensitivity analysis of parameteric and stochastic uncertainties wrt time-dependent Qols



Figs courtesy of Joy Bahr-Mueller

What else

What is in UQTk but not in PyTUQ:

Low-rank tensor (canonical) decomposition

Sparse quadrature

Weighted BCS

PC germ maps

Non-standard, custom PC

Transitional MCMC, Single-site MCMC

Some evidence computation scripts

Data-free inference

Intrusive arithmetics

Coming up (hopefully):

Variational Inference

More optimization routines

More tests needed

More workflows

Math documentation/manual

Usage tutorial of some sort?

Talk at SIAM UQ 26

Part of FASTMath Software catalogue

Any more ideas/questions?